

Accelerator Series FPGAs – ACT 3 Family

Features

- Up to 10,000 Gate Array Equivalent Gates (up to 25,000 equivalent PLD Gates)
- Highly Predictable Performance with 100% Automatic Placeand-Route
- As Low as 9.0 ns Clock-to-Output Times (-1 Speed Grade)
- Up to 186 MHz On-Chip Performance (-1 Speed Grade)
- Up to 228 User-Programmable I/O Pins
- Four Fast, Low-Skew Clock Networks

- More than 500 Macro Functions
- Replaces up to Twenty 32 Macro-Cell CPLDs
- Replaces up to One Hundred 20-Pin PAL[®] Packages
- Up to 1,153 Dedicated Flip-Flops
- VQFP, TQFP, BGA, and PQFP Packages
- Nonvolatile, User Programmable
- Fully Tested Prior to Shipment
- 5.0 V and 3.3 V Versions
- · Optimized for Logic Synthesis Methodologies
- Low Power CMOS Technology

Table 1 • ACT 3 Family Product Information

| Device | A1415 | A1425 | A1440 | A1460 | A14100 |
|--|--------------------|--------------------|--------------------|--------------------|--------|
| Capacity | | | | • | |
| Gate Array Equivalent Gates | 1,500 | 2,500 | 4,000 | 6,000 | 10,000 |
| PLD Equivalent Gates | 3,750 | 6,250 | 10,000 | 15,000 | 25,000 |
| TTL Equivalent Package (40 gates) | 40 | 60 | 100 | 150 | 250 |
| 20-Pin PAL Equivalent Packages (100 gates) | 15 | 25 | 40 | 60 | 100 |
| Logic Modules | 200 | 310 | 564 | 848 | 1,377 |
| S-Module | 104 | 160 | 288 | 432 | 697 |
| C-Module | 96 | 150 | 276 | 416 | 680 |
| Dedicated Flip-Flops ¹ | 264 | 360 | 568 | 768 | 1,153 |
| User I/Os (maximum) | 80 | 100 | 140 | 168 | 228 |
| Maximum Performance ² (worst-case commercial, - | -1 speed grade) | | | | |
| Chip-to-Chip ³ (MHz) | 80 | 80 | 80 | 78 | 76 |
| Accumulators (16-bit, MHz) | 47 | 47 | 47 | 47 | 47 |
| Loadable Counter (16-bit, MHz) | 82 | 82 | 82 | 82 | 78 |
| Prescaled Loadable Counters (16-bit, MHz) | 186 | 186 | 186 | 150 | 150 |
| Datapath, Shift Registers (MHz) | 186 | 186 | 186 | 150 | 150 |
| Clock-to-Output (pad-to-pad, ns) | 9.0 | 9.0 | 9.5 | 10.0 | 10.5 |
| Packages ⁴ (by pin count) | | | | | |
| CPGA | PG100 ⁵ | PG133 ⁵ | PG175 ⁵ | PG207 | PG257 |
| PLCC | PL84 | PL84 | PL84 | - | - |
| PQFP | PQ100 | PQ100, PQ160 | PQ160 | PQ160, PQ208 | _ |
| RQFP | - | - | _ | - | RQ208 |
| VQFP | VQ100 | VQ100 | VQ100 | - | _ |
| TQFP | _ | - | TQ176 | TQ176_ | _ |
| BGA | _ | - | _ | BG225 ⁵ | BG313 |
| CQFP | _ | CQ132 | - | CQ196 | CQ256 |

Notes:

1. One flip-flop per S0Module, two flip-flops per I/O Module.

2. Based on A1415A-1, A1425A-1, A1440A-1, A1460A-1, and A14100A-1.

3. Clock-to-Output (pad-to-pad) + assumed trace delay + setup time. Refer to the "System Performance Model" on page 1-1 and Table 1-1 on page 1-2.

4. See the "Product Plan" table on page III for package availability.

5. Discontinued device and package combination.

 –2 and –3 speed grades have been discontinued. For more information about discontinued devices, refer to the Product Discontinuation Notices (PDNs) listed below, available on the Microsemi SoC Products Group website: PDN March 2001, PDN 0104, PDN 0203, PDN 0604, PDN 1004



Ordering Information



Notes:

- 1. The -2 and -3 speed grades have been discontinued.
- The Ceramic Pin Grid Array packages PG100, PG133, and PG175 have been discontinued in all device densities, speed grades, and temperature grades.
 The Plastic Ball Grid Array package BG225 has been discontinued in all device densities (specifically for A1460A), all speed
- 3. The Plastic Ball Grid Array package BG225 has been discontinued in all device densities (specifically for A1460A), all speed grades, and all temperature grades.
- 4. Military Grade devices are no longer available for the A1440A device.
- For more information about discontinued devices, refer to the Product Discontinuation Notices (PDNs) listed below, available on the Microsemi SoC Products Group website: PDN March 2001

PDN 0104 PDN 0203 PDN 0604 PDN 1004

Product Plan

| | | Speed | Grade ¹ | Application ¹ | | | | |
|---|-----------------------|-------|--------------------|--------------------------|---|---|---|---|
| Device/Package | Std. | -1 | -2 | -3 | С | I | М | В |
| A1415A Device | • | • | | | • | | | |
| 84-Pin Plastic Leaded Chip Carrier (PLCC) | ✓ | 1 | D | D | 1 | 1 | 1 | - |
| 100-Pin Plastic Quad Flatpack (PQFP) | ✓ | 1 | D | D | 1 | 1 | 1 | - |
| 100-Pin Very Thin Quad Flatpack (VQFP) | 1 | 1 | D | D | 1 | ✓ | 1 | - |
| 100-Pin Ceramic Pin Grid Array (CPGA) | D | D | D | D | D | - | - | _ |
| A14V15A Device | | | • | | • | | • | |
| 84-Pin Plastic Leaded Chip Carrier (PLCC) | ✓ | - | - | - | 1 | - | — | - |
| 100-Pin Very Thin Quad Flatpack (VQFP) | ✓ | - | - | - | 1 | - | - | - |
| A1425A Device | | | • | | • | | • | |
| 84-Pin Plastic Leaded Chip Carrier (PLCC) | ✓ | 1 | D | D | 1 | 1 | | |
| 100-Pin Plastic Quad Flatpack (PQFP) | 1 | 1 | D | D | 1 | 1 | _ | - |
| 100-Pin Very Thin Quad Flatpack (VQFP) | 1 | 1 | D | D | 1 | 1 | _ | - |
| 132-Pin Ceramic Quad Flatpack (CQFP) | ✓ | 1 | - | - | 1 | - | 1 | 1 |
| 133-Pin Ceramic Pin Grid Array (CPGA) | D | D | D | D | D | - | D | D |
| 160-Pin Plastic Quad Flatpack (PQFP) | 1 | 1 | D | D | 1 | 1 | - | _ |
| A14V25A Device | | | | | | | | |
| 84-Pin Plastic Leaded Chip Carrier (PLCC) | ✓ | - | - | - | 1 | _ | _ | - |
| 100-Pin Very Thin Quad Flatpack (VQFP) | ✓ | - | - | - | 1 | - | - | - |
| 160-Pin Plastic Quad Flatpack (PQFP) | ✓ | - | - | - | 1 | - | - | - |
| A1440A Device | | | | | 1 | | | 1 |
| 84-Pin Plastic Leaded Chip Carrier (PLCC) | ✓ | 1 | D | D | 1 | 1 | — | - |
| 100-Pin Very Thin Quad Flatpack (VQFP) | 1 | 1 | D | D | 1 | 1 | _ | - |
| 160-Pin Plastic Quad Flatpack (PQFP) | ~ | 1 | D | D | 1 | 1 | _ | - |
| 175-Pin Ceramic Pin Grid Array (CPGA) | D | D | D | D | D | - | - | - |
| 176-Pin Thin Quad Flatpack (TQFP) | 1 | 1 | D | D | 1 | 1 | - | _ |

Notes:

1. Applications: C = Commercial I = Industrial

M = Military

2. Commercial only

Availability: $\checkmark = Available$ P = Planned

- = Not plannedD = Discontinued

Speed Grade: -1 = Approx. 15% faster than Std. -2 = Approx. 25% faster than Std. -3 = Approx. 35% faster than Std. (-2 and -3 speed grades have been discontinued.)

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Accelerator Series FPGAs - ACT 3 Family

| | | Speed | Grade ¹ | Application ¹ | | | | |
|---|------|-------|--------------------|--------------------------|---|-----------------------|---|----------|
| Device/Package | Std. | -1 | -2 | -3 | С | I | м | В |
| A14V40A Device | | 1 | 1 | 1 | • | | • | |
| 84-Pin Plastic Leaded Chip Carrier (PLCC) | 1 | - | - | - | 1 | - | - | - |
| 100-Pin Very Thin Quad Flatpack (VQFP) | 1 | _ | _ | _ | 1 | _ | _ | - |
| 160-Pin Plastic Quad Flatpack (PQFP) | 1 | _ | _ | _ | 1 | - | - | - |
| 176-Pin Thin Quad Flatpack (TQFP) | 1 | _ | _ | _ | 1 | _ | - | - |
| A1460A Device | | | | | | | | I |
| 160-Pin Plastic Quad Flatpack (PQFP) | 1 | ✓ | D | D | ✓ | ✓ | _ | - |
| 176-Pin Thin Quad Flatpack (TQFP) | ✓ | 1 | D | D | ✓ | ✓ | - | - |
| 196-Pin Ceramic Quad Flatpack (CQFP) | 1 | 1 | - | - | 1 | - | 1 | 1 |
| 207-Pin Ceramic Pin Grid Array (CPGA) | 1 | ~ | D | D | ✓ | - | 1 | 1 |
| 208-Pin Plastic Quad Flatpack (PQFP) | 1 | ~ | D | D | ✓ | ✓ | - | - |
| 225-Pin Plastic Ball Grid Array (BGA) | D | D | D | D | D | - | - | - |
| A14V60A Device | • | | | • | | • | | |
| 160-Pin Plastic Quad Flatpack (PQFP) | ✓ | _ | - | _ | ✓ | - | - | - |
| 176-Pin Thin Quad Flatpack (TQFP) | ✓ | - | - | - | 1 | - | - | - |
| 208-Pin Plastic Quad Flatpack (PQFP) | ✓ | _ | _ | _ | ✓ | - | - | - |
| A14100A Device | | | | | | | | |
| 208-Pin Power Quad Flatpack (RQFP) | 1 | ✓ | D | D | ✓ | 1 | - | - |
| 257-Pin Ceramic Pin Grid Array (CPGA) | ✓ | ✓ | D | D | ✓ | - | ✓ | 1 |
| 313-Pin Plastic Ball Grid Array (BGA) | 1 | ✓ | D | D | 1 | - | - | - |
| 256-Pin Ceramic Quad Flatpack (CQFP) | 1 | 1 | - | - | 1 | - | ✓ | 1 |
| A14V100A Device | • | • | • | • | • | | • | |
| 208-Pin Power Quad Flatpack (RQFP) | ✓ | - | - | - | 1 | - | - | - |
| 313-Pin Plastic Ball Grid Array (BGA) | 1 | _ | - | - | 1 | - | - | _ |

Notes:

1. Applications: C = CommercialI = Industrial
M = Military
Commercial only Availability:

✓ = Available

P = Planned- = Not planned

D = Discontinued

Speed Grade:

-1 = Approx. 15% faster than Std. -2 = Approx. 25% faster than Std. -3 = Approx. 35% faster than Std. (-2 and -3 speed grades have been discontinued.)

Plastic Device Resources

| Device | Logic | user I/Os | | | | | | | | |
|--------|---------|-----------|------|-------|-------|----------|-------|-------|--------|-------|
| Series | Modules | Gates | PL84 | PQ100 | PQ160 | PQ/RQ208 | VQ100 | TQ176 | BG225* | BG313 |
| A1415 | 200 | 1500 | 70 | 80 | - | - | 80 | - | - | - |
| A1425 | 310 | 2500 | 70 | 80 | 100 | - | 83 | - | - | _ |
| A1440 | 564 | 4000 | 70 | - | 131 | - | 83 | 140 | - | - |
| A1460 | 848 | 6000 | - | - | 131 | 167 | - | 151 | 168 | - |
| A14100 | 1377 | 10000 | - | - | - | 175 | - | - | - | 228 |

Note: *Discontinued

Hermetic Device Resources

| Device | Logic | | User I/Os | | | | | | | | | |
|--------|---------|-------|-----------|--------|--------|-------|-------|-------|-------|-------|--|--|
| Series | Modules | Gates | PG100* | PG133* | PG175* | PG207 | PG257 | CQ132 | CQ196 | CQ256 | | |
| A1415 | 200 | 1500 | 80 | - | - | - | _ | - | - | - | | |
| A1425 | 310 | 2500 | - | 100 | _ | - | _ | 100 | - | - | | |
| A1440 | 564 | 4000 | - | - | 140 | - | _ | - | - | - | | |
| A1460 | 848 | 6000 | - | - | - | 168 | _ | - | 168 | - | | |
| A14100 | 1377 | 10000 | - | - | _ | - | 228 | - | - | 228 | | |

Note: *Discontinued

Contact your local Microsemi SoC Products Group (formerly Actel) representative for device availability: http://www.microsemi.com/soc/contact/default.aspx.



ACT 3 Family Overview

| General Description | 1-1 |
|-------------------------|-----|
| Detailed Specifications | |
| Topology | 2-1 |
| Logic Modules | 2-2 |
| //Os | 2-3 |

| 1/03 | | | | | | | |
|--------------------------------|----|------|------|------|------|------|----------|
| Clock Networks | | | | | | | 2-4 |
| Routing Structure | | | | | | | 2-5 |
| 5 V Operating Conditions | | | | | | | 2-9 |
| 3.3 V Operating Conditions | | | | | | | 2-10 |
| Package Thermal Characteristic | cs | | | | | | 2-11 |
| ACT 3 Timing Model | | | | | | | 2-16 |
| Pin Descriptions | | | | | | | 2-42 |

Package Pin Assignments

| PL84 | |
|--------------|------|
| PQ100 | |
| PQ160 | 3-5 |
| PQ208, RQ208 | |
| VQ100 | 3-12 |
| CQ132 | |
| CQ196 | |
| CQ256 | |
| BG225 | 3-20 |
| BG313 | |
| PG100 | 3-24 |
| PG133 | |
| PG175 | 3-28 |
| PG207 | |
| PG257 | 3-32 |
| | |

Datasheet Information

| List of Changes | 4-1 |
|---|-----|
| Datasheet Categories | 4-3 |
| Safety Critical, Life Support, and High-Reliability Applications Policy | 4-3 |



1 – ACT 3 Family Overview

General Description

Microsemi's ACT 3 Accelerator Series of FPGAs offers the industry's fastest high-capacity programmable logic device. ACT 3 FPGAs offer a high performance, PCI compliant programmable solution capable of 186 MHz on-chip performance and 9.0 nanosecond clock-to-output (-1 speed grade), with capacities spanning from 1,500 to 10,000 gate array equivalent gates.

The ACT 3 family builds on the proven two-module architecture consisting of combinatorial and sequential logic modules used in Microsemi's 3200DX and 1200XL families. In addition, the ACT 3 I/O modules contain registers which deliver 9.0 nanosecond clock-to-out times (-1 speed grade). The devices contain four clock distribution networks, including dedicated array and I/O clocks, supporting very fast synchronous and asynchronous designs. In addition, routed clocks can be used to drive high fanout signals such as flip-flop resets and output.

The ACT 3 family is supported by Microsemi's Designer Series Development System which offers automatic placement and routing (with automatic or fixed pin assignments), static timing analysis, user programming, and debug and diagnostic probe capabilities.





System Performance Model





| Device and Speed Grade | t _{CKHS} (ns) | t _{TRACE} (ns) | t _{INSU} (ns) | Total (ns) | MHz |
|---------------------------|------------------------|-------------------------|------------------------|------------|-----|
| A1425A -3 | 7.5 | 1.0 | 1.8 | 10.3 | 97 |
| A1460A -3 | 9.0 | 1.0 | 1.3 | 11.3 | 88 |
| A1425A -2 | 7.5 | 1.0 | 2.0 | 10.5 | 95 |
| A1460A -2 | 9.0 | 1.0 | 1.5 | 11.5 | 87 |
| A1425A -1 | 9.0 | 1.0 | 2.3 | 12.3 | 81 |
| A1460A -1 | 10.0 | 1.0 | 1.8 | 12.8 | 78 |
| A1425A STD | 10.0 | 1.0 | 2.7 | 13.7 | 73 |
| A1460A STD | 11.5 | 1.0 | 2.0 | 14.5 | 69 |

Table 1-1 • Chip-to-Chip Performance (worst-case commercial)

Note: The –2 and –3 speed grades have been discontinued. Refer to PDN 0104, PDN 0203, PDN 0604, and PDN 1004 at http://www.microsemi.com/soc/support/notifications/default.aspx#pdn.



2 – Detailed Specifications

This section of the datasheet is meant to familiarize the user with the architecture of the ACT 3 family of FPGA devices. A generic description of the family will be presented first, followed by a detailed description of the logic blocks, the routing structure, the antifuses, and the special function circuits. The on-chip circuitry required to program the devices is not covered.

Topology

The ACT 3 family architecture is composed of six key elements: Logic modules, I/O modules, I/O Pad Drivers, Routing Tracks, Clock Networks, and Programming and Test Circuits. The basic structure is similar for all devices in the family, differing only in the number of rows, columns, and I/Os. The array itself consists of alternating rows of modules and channels. The logic modules and channels are in the center of the array; the I/O modules are located along the array periphery. A simplified floor plan is depicted in Figure 2-1.



Figure 2-1 • Generalized Floor Plan of ACT 3 Device



Logic Modules

ACT 3 logic modules are enhanced versions of the 1200XL family logic modules. As in the 1200XL family, there are two types of modules: C-modules and S-modules (Figure 2-2 and Figure 2-3). The C-module is functionally equivalent to the 1200XL C-module and implements high fanin combinatorial macros, such as 5-input AND, 5-input OR, and so on. It is available for use as the CM8 hard macro. The S-module is designed to implement high-speed sequential functions within a single module.



Figure 2-2 • C-Module Diagram



Figure 2-3 • S-Module Diagram

S-modules consist of a full C-module driving a flip-flop, which allows an additional level of logic to be implemented without additional propagation delay. It is available for use as the DFM8A/B and DLM8A/B hard macros. C-modules and S-modules are arranged in pairs called module-pairs. Module-pairs are arranged in alternating patterns and make up the bulk of the array. This arrangement allows the placement software to support two-module macros of four types (CC, CS, SC, and SS). The C-module implements the following function:

EQ 1

where: S0 = A0 * B0 and S1 = A1 + B1



The S-module contains a full implementation of the C-module plus a clearable sequential element that can either implement a latch or flip-flop function. The S-module can therefore implement any function implemented by the C-module. This allows complex combinatorial-sequential functions to be implemented with no delay penalty. The Designer Series Development System will automatically combine any C-module macro driving an S-module macro into the S-module, thereby freeing up a logic module and eliminating a module delay.

The clear input CLR is accessible from the routing channel. In addition, the clock input may be connected to one of three clock networks: CLKA, CLKB, or HCLK. The C-module and S-module functional descriptions are shown in Figure 2-2 and Figure 2-3 on page 2-2. The clock selection is determined by a multiplexer select at the clock input to the S-module.

I/Os

I/O Modules

I/O modules provide an interface between the array and the I/O Pad Drivers. I/O modules are located in the array and access the routing channels in a similar fashion to logic modules. The I/O module schematic is shown in Figure 4. The signals DataIn and DataOut connect to the I/O pad driver.



Figure 2-4 • Functional Diagram for I/O Module

Each I/O module contains two D-type flip-flops. Each flip-flop is connected to the dedicated I/O clock (IOCLK). Each flip-flop can be bypassed by nonsequential I/Os. In addition, each flip-flop contains a data enable input that can be accessed from the routing channels (ODE and IDE). The asynchronous preset/clear input is driven by the dedicated preset/clear network (IOPCL). Either preset or clear can be selected individually on an I/O module by I/O module basis.



The I/O module output Y is used to bring Pad signals into the array or to feed the output register back into the array. This allows the output register to be used in high-speed state machine applications. Side I/O modules have a dedicated output segment for Y extending into the routing channels above and below (similar to logic modules). Top/Bottom I/O modules have no dedicated output segment. Signals coming into the chip from the top or bottom are routed using F-fuses and LVTs (F-fuses and LVTs are explained in detail in the routing section).

I/O Pad Drivers

All pad drivers are capable of being tristate. Each buffer connects to an associated I/O module with four signals: OE (Output Enable), IE (Input Enable), DataOut, and DataIn. Certain special signals used only during programming and test also connect to the pad drivers: OUTEN (global output enable), INEN (global input enable), and SLEW (individual slew selection). See Figure 2-5.



Figure 2-5 • Function Diagram for I/O Pad Driver

Special I/Os

The special I/Os are of two types: temporary and permanent. Temporary special I/Os are used during programming and testing. They function as normal I/Os when the MODE pin is inactive. Permanent special I/Os are user programmed as either normal I/Os or special I/Os. Their function does not change once the device has been programmed. The permanent special I/Os consist of the array clock input buffers (CLKA and CLKB), the hard-wired array clock input buffer (HCLK), the hard-wired I/O clock input buffer (IOCLK), and the hard-wired I/O register preset/clear input buffer (IOPCL). Their function is determined by the I/O macros selected.

Clock Networks

The ACT 3 architecture contains four clock networks: two high-performance dedicated clock networks and two general purpose routed networks. The high-performance networks function up to 200 MHz, while the general purpose routed networks function up to 150 MHz.



Dedicated Clocks

Dedicated clock networks support high performance by providing sub-nanosecond skew and guaranteed performance. Dedicated clock networks contain no programming elements in the path from the I/O Pad Driver to the input of S-modules or I/O modules. There are two dedicated clock networks: one for the array registers (HCLK), and one for the I/O registers (IOCLK). The clock networks are accessed by special I/Os.



Figure 2-6 • Clock Networks

The routed clock networks are referred to as CLK0 and CLK1. Each network is connected to a clock module (CLKMOD) that selects the source of the clock signal and may be driven as follows (Figure 2-6):

- Externally from the CLKA pad
- Externally from the CLKB pad
- Internally from the CLKINA input
- Internally from the CLKINB input

The clock modules are located in the top row of I/O modules. Clock drivers and a dedicated horizontal clock track are located in each horizontal routing channel. The function of the clock module is determined by the selection of clock macros from the macro library. The macro CLKBUF is used to connect one of the two external clock pins to a clock network, and the macro CLKINT is used to connect an internally generated clock signal to a clock network. Since both clock networks are identical, the user does not care whether CLK0 or CLK1 is being used. Routed clocks can also be used to drive high fanout nets like resets, output enables, or data enables. This saves logic modules and results in performance increases in some cases.

Routing Structure

The ACT 3 architecture uses vertical and horizontal routing tracks to connect the various logic and I/O modules. These routing tracks are metal interconnects that may either be of continuous length or broken into segments. Segments can be joined together at the ends using antifuses to increase their lengths up to the full length of the track.



Horizontal Routing

Horizontal channels are located between the rows of modules and are composed of several routing tracks. The horizontal routing tracks within the channel are divided into one or more segments. The minimum horizontal segment length is the width of a module-pair, and the maximum horizontal segment length is the full length of the channel. Any segment that spans more than one-third the row length is considered a long horizontal segment. A typical channel is shown in Figure 2-7. Undedicated horizontal routing tracks are used to route signal nets. Dedicated routing tracks are used for the global clock networks and for power and ground tie-off tracks.



Figure 2-7 • Horizontal Routing Tracks and Segments

Vertical Routing

Other tracks run vertically through the modules. Vertical tracks are of three types: input, output, and long. Vertical tracks are also divided into one or more segments. Each segment in an input track is dedicated to the input of a particular module. Each segment in an output track is dedicated to the output of a particular module. Long segments are uncommitted and can be assigned during routing. Each output segment spans four channels (two above and two below), except near the top and bottom of the array where edge effects occur. LVTs contain either one or two segments. An example of vertical routing tracks and segments is shown in Figure 2-8.



Figure 2-8 • Vertical Routing Tracks and Segments

Antifuse Connections

An antifuse is a "normally open" structure as opposed to the normally closed fuse structure used in PROMs or PALs. The use of antifuses to implement a programmable logic device results in highly testable structures as well as an efficient programming architecture. The structure is highly testable because there are no preexisting connections; temporary connections can be made using pass transistors. These temporary connections can isolate individual antifuses to be programmed as well as isolate individual circuit structures to be tested. This can be done both before and after programming. For example, all metal tracks can be tested for continuity and shorts between adjacent tracks, and the functionality of all logic modules can be verified.

Four types of antifuse connections are used in the routing structure of the ACT 3 array. (The physical structure of the antifuse is identical in each case; only the usage differs.)

Table 2-1 shows four types of antifuses.

| Table 2-1 • | Antifuse | Types |
|-------------|----------|-------|
|-------------|----------|-------|

| Туре | Description |
|------|-------------------------------------|
| XF | Horizontal-to-vertical connection |
| HF | Horizontal-to-horizontal connection |
| VF | Vertical-to-vertical connection |
| FF | "Fast" vertical connection |

Examples of all four types of connections are shown in Figure 2-7 on page 2-6 and Figure 2-8 on page 2-6.

Module Interface

Connections to Logic and I/O modules are made through vertical segments that connect to the module inputs and outputs. These vertical segments lie on vertical tracks that span the entire height of the array.

Module Input Connections

The tracks dedicated to module inputs are segmented by pass transistors in each module row. During normal user operation, the pass transistors are inactive, which isolates the inputs of a module from the inputs of the module directly above or below it. During certain test modes, the pass transistors are active to verify the continuity of the metal tracks. Vertical input segments span only the channel above or the channel below. The logic modules are arranged such that half of the inputs are connected to the channel above and half of the inputs to segments in the channel below, as shown in Figure 2-9.



Figure 2-9 • Logic Module Routing Interface



Module Output Connections

Module outputs have dedicated output segments. Output segments extend vertically two channels above and two channels below, except at the top or bottom of the array. Output segments twist, as shown in Figure 10, so that only four vertical tracks are required.

LVT Connections

Outputs may also connect to nondedicated segments called Long Vertical Tracks (LVTs). Each module pair in the array shares four LVTs that span the length of the column. Any module in the column pair can connect to one of the LVTs in the column using an FF connection. The FF connection uses antifuses connected directly to the driver stage of the module output, bypassing the isolation transistor. FF antifuses are programmed at a higher current level than HF, VF, or XF antifuses to produce a lower resistance value.

Antifuse Connections

In general every intersection of a vertical segment and a horizontal segment contains an unprogrammed antifuse (XF-type). One exception is in the case of the clock networks.

Clock Connections

To minimize loading on the clock networks, a subset of inputs has antifuses on the clock tracks. Only a few of the C-module and S-module inputs can be connected to the clock networks. To further reduce loading on the clock network, only a subset of the horizontal routing tracks can connect to the clock inputs of the S-module.

Programming and Test Circuits

The array of logic and I/O modules is surrounded by test and programming circuits controlled by the temporary special I/O pins MODE, SDI, and DCLK. The function of these pins is similar to all ACT family devices. The ACT 3 family also includes support for two Actionprobe[®] circuits, allowing complete observability of any logic or I/O module in the array using the temporary special I/O pins, PRA and PRB.

5 V Operating Conditions

| Symbol | Parameter | Limits | Units |
|------------------|--------------------------------------|-------------------|-------|
| VCC | DC supply voltage | -0.5 to +7.0 | V |
| VI | Input voltage | -0.5 to VCC + 0.5 | V |
| VO | Output voltage | -0.5 to VCC + 0.5 | V |
| IIO | I/O source sink current ² | ±20 | mA |
| T _{STG} | Storage temperature | -65 to +150 | °C |

Table 2-2 • Absolute Maximum Ratings¹, Free Air Temperature Range

Notes:

1. Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. Exposure to absolute maximum rated conditions for extended periods may affect device reliability. Device should not be operated outside the recommended operating conditions.

2. Device inputs are normally high impedance and draw extremely low current. However, when input voltage is greater than VCC + 0.5 V for less than GND –0.5 V, the internal protection diodes will forward bias and can draw excessive current.

Table 2-3 • Recommended Operating Conditions

| Parameter | Commercial | Industrial | Military | Units |
|----------------------------|------------|------------|-------------|-------|
| Temperature range* | 0 to +70 | -40 to +85 | -55 to +125 | °C |
| 5 V power supply tolerance | ±5 | ±10 | ±10 | %VCC |

Note: *Ambient temperature (T_A) is used for commercial and industrial; case temperature (T_C) is used for military.

| | | | Со | nmercial | In | dustrial | Ν | Ailitary | |
|--------------------|--------------------------------|---------------------------------|----------|-------------|------|-----------|------|-----------|-------|
| Symbol | Parameter | Test Condition | Min. | Max. | Min. | Max. | Min. | Max. | Units |
| VOH ^{1,2} | High level output | IOH = –4 mA (CMOS) | - | - | 3.7 | - | 3.7 | _ | V |
| | | IOH = –6 mA (CMOS) | 3.84 | | | | | | V |
| | | IOH = –10 mA (TTL) ³ | 2.40 | | | | | | V |
| VOL ^{1,2} | Low level output | IOL = +6 mA (CMOS) | | 0.33 | | 0.4 | | 0.4 | V |
| | | IOL = +12 mA (TTL) ³ | | 0.50 | | | | | |
| VIH | High level input | TTL inputs | 2.0 | VCC + 0.3 | 2.0 | VCC + 0.3 | 2.0 | VCC + 0.3 | V |
| VIL | Low level input | TTL inputs | -0.3 | 0.8 | -0.3 | 0.8 | -0.3 | 0.8 | V |
| IIN | Input leakage | VI = VCC or GND | -10 | +10 | -10 | +10 | -10 | +10 | μA |
| IOZ | 3-state output leakage | VO = VCC or GND | -10 | +10 | -10 | +10 | -10 | +10 | μA |
| C _{IO} | I/O capacitance ^{3,4} | | | 10 | | 10 | | 10 | pF |
| ICC(S) | Standby VCC supply cu | irrent (typical = 0.7 mA) | | 2 | | 10 | | 20 | mA |
| ICC(D) | Dynamic VCC supply c | urrent. See the Power Dis | ssipatio | on section. | • | | | • | |
| | • | | | | | | | | |

Table 2-4 • Electrical Specifications

Notes:

1. Microsemi devices can drive and receive either CMOS or TTL signal levels. No assignment of I/Os as TTL or CMOS is required.

2. Tested one output at a time, VCC = minimum.

3. Not tested; for information only.

4. VOUT = 0 V, f = 1 MHz

5. Typical standby current = 0.7 mA. All outputs unloaded. All inputs = VCC or GND.



3.3 V Operating Conditions

| Symbol | Parameter | Limits | Units |
|------------------|--------------------------------------|-------------------|-------|
| VCC | DC supply voltage | -0.5 to +7.0 | V |
| VI | Input voltage | -0.5 to VCC + 0.5 | V |
| VO | Output voltage | -0.5 to VCC + 0.5 | V |
| IIO | I/O source sink current ² | ±20 | mA |
| T _{STG} | Storage temperature | -65 to +150 | °C |

Table 2-5 • Absolute Maximum Ratings¹, Free Air Temperature Range

Notes:

1. Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. Exposure to absolute maximum rated conditions for extended periods may affect device reliability. Device should not be operated outside the recommended operating conditions.

2. Device inputs are normally high impedance and draw extremely low current. However, when input voltage is greater than VCC + 0.5 V for less than GND –0.5 V, the internal protection diodes will forward bias and can draw excessive current.

Table 2-6 • Recommended Operating Conditions

| Parameter | Commercial | Units |
|------------------------|------------|-------|
| Temperature range* | 0 to +70 | °C |
| Power supply tolerance | 3.0 to 3.6 | V |

Note: *Ambient temperature (T_A) is used for commercial.

Table 2-7 • Electrical Specifications

| | | Commercial | | |
|--|-----------------|------------|-----------|-------|
| Parameter | | Min. | Max. | Units |
| VOH ¹ | IOH = -4 mA | 2.15 | _ | V |
| | IOH = -3.2 mA | 2.4 | | V |
| VOL ¹ | IOL = 6 mA | | 0.4 | V |
| VIL | | -0.3 | 0.8 | V |
| VIH | | 2.0 | VCC + 0.3 | V |
| Input transition time t _R , t _F ² | VI = VCC or GND | -10 | +10 | μA |
| C _{IO} I/O Capacitance ^{2,3} | | | 10 | pF |
| Standby current, ICC ⁴ (typical = 0.3 mÅ) | | | 0.75 | mA |
| Leakage current ⁵ | | -10 | 10 | μA |

1. Only one output tested at a time. VCC = minimum.

2. Not tested; for information only.

3. Includes worst-case 84-pin PLCC package capacitance. VOUT = 0 V, f - 1 MHz.

4. Typical standby current = 0.3 mA. All outputs unloaded. All inputs = VCC or GND.

5. VO, VIN = VCC or GND



Package Thermal Characteristics

The device junction to case thermal characteristic is θ jc, and the junction to ambient air characteristic is θ ja. The thermal characteristics for θ ja are shown with two different air flow rates.

Maximum junction temperature is 150°C.

A sample calculation of the absolute maximum power dissipation allowed for a CPGA 175-pin package at commercial temperature and still air is as follows:

$$\frac{\text{Max. junction temp. (°C)} - \text{Max. ambient temp. (°C)}}{\theta_{ja} °C/W} = \frac{150°C - 70°C}{25°C/W} = 3.2 \text{ W}$$

EQ 2

| Package Type∗ | Pin Count | θ _{jc} | θ _{ja} Still Air | θ _{ja} 300 ft./min. | Units |
|-----------------------------|-----------|-----------------|------------------------------|---------------------------------|-------|
| Ceramic Pin Grid Array | 100 | 20 | 35 | 17 | °C/W |
| | 133 | 20 | 30 | 15 | °C/W |
| | 175 | 20 | 25 | 14 | °C/W |
| | 207 | 20 | 22 | 13 | °C/W |
| | 257 | 20 | 15 | 8 | °C/W |
| Ceramic Quad Flatpack | 132 | 13 | 55 | 30 | °C/W |
| | 196 | 13 | 36 | 24 | °C/W |
| | 256 | 13 | 30 | 18 | °C/W |
| Plastic Quad Flatpack | 100 | 13 | 51 | 40 | °C/W |
| | 160 | 10 | 33 | 26 | °C/W |
| | 208 | 10 | 33 | 26 | °C/W |
| Very Thin Quad Flatpack | 100 | 12 | 43 | 35 | °C/W |
| Thin Quad Flatpack | 176 | 11 | 32 | 25 | °C/W |
| Power Quad Flatpack | 208 | 0.4 | 17 | 13 | °C/W |
| Plastic Leaded Chip Carrier | 84 | 12 | 37 | 28 | °C/W |
| Plastic Ball Grid Array | 225 | 10 | 25 | 19 | °C/W |
| | 313 | 10 | 23 | 17 | °C/W |

Table 2-8 • Package Thermal Characteristics

Note: Maximum power dissipation in still air:

PQ160 = 2.4 W PQ208 = 2.4 W PQ100 = 1.6 W VQ100 = 1.9 W TQ176 = 2.5 W PL84 = 2.2 W RQ208 = 4.7 W BG225 = 3.2 W BG313 = 3.5 W



Power Dissipation

P = [ICC standby + lactive] * VCC * IOL * VOL * N + IOH* (VCC - VOH) * M

where:

ICC standby is the current flowing when no inputs or outputs are changing

lactive is the current flowing due to CMOS switching.

IOL and IOH are TTL sink/source current.

VOL and VOH are TTL level output voltages.

N is the number of outputs driving TTL loads to VOL.

M equals the number of outputs driving TTL loads to VOH.

An accurate determination of N and M is problematical because their values depend on the design and on the system I/O. The power can be divided into two components: static and active.

Static Power Component

Microsemi FPGAs have small static power components that result in lower power dissipation than PALs or PLDs. By integrating multiple PALs/PLDs into one FPGA, an even greater reduction in board-level power dissipation can be achieved.

The power due to standby current is typically a small component of the overall power. Standby power is calculated in Table 2-9 for commercial, worst case conditions.

Table 2-9 • Standby Power Calculation

| ICC | VCC | Power |
|------|--------|---------|
| 2 mA | 5.25 V | 10.5 mW |

The static power dissipated by TTL loads depends on the number of outputs driving high or low and the DC load current. Again, this value is typically small. For instance, a 32-bit bus sinking 4 mA at 0.33 V will generate 42 mW with all outputs driving low, and 140 mW with all outputs driving high. The actual dissipation will average somewhere between as I/Os switch states with time.

Active Power Component

Power dissipation in CMOS devices is usually dominated by the active (dynamic) power dissipation. This component is frequency dependent, a function of the logic and the external I/O. Active power dissipation results from charging internal chip capacitances of the interconnect, unprogrammed antifuses, module inputs, and module outputs, plus external capacitance due to PC board traces and load device inputs.

An additional component of the active power dissipation is the totem-pole current in CMOS transistor pairs. The net effect can be associated with an equivalent capacitance that can be combined with frequency and voltage to represent active power dissipation.

Equivalent Capacitance

The power dissipated by a CMOS circuit can be expressed by EQ 4.

Power (μ W) = C_{EQ} * VCC² * F

EQ 4

EQ 3

Where:

 C_{EQ} is the equivalent capacitance expressed in pF.

VCC is the power supply in volts.

F is the switching frequency in MHz.



Equivalent capacitance is calculated by measuring ICC active at a specified frequency and voltage for each circuit component of interest. Measurements have been made over a range of frequencies at a fixed value of VCC. Equivalent capacitance is frequency independent so that the results may be used over a wide range of operating conditions. Equivalent capacitance values are shown in Figure 2-10.

| Item | CEQ Value |
|--|-----------|
| Modules (C _{EQM}) | 6.7 |
| Input Buffers (C _{EQI}) | 7.2 |
| Output Buffers (C _{EQO}) | 10.4 |
| Routed Array Clock Buffer Loads (C _{EQCR}) | 1.6 |
| Dedicated Clock Buffer Loads (C _{EQCD}) | 0.7 |
| I/O Clock Buffer Loads (C _{EQCI)} | 0.9 |

To calculate the active power dissipated from the complete design, the switching frequency of each part of the logic must be known. EQ 5 shows a piece-wise linear summation over all components.

Power =VCC² * [(m * C_{EQM} * f_m)_{modules} + (n * C_{EQI} * f_n) inputs

+ ($p * (C_{EQO} + C_L) * f_p$)outputs

+ 0.5 * (q1 * C_{EQCR} * f_{q1})_{routed_Clk1} + (r1 * fq1)_{routed_Clk1}

+ 0.5 * (q2 * C_{EQCR} * fq2)_{routed_Clk2}

+ $(r_2 * f_{q2})_{routed_Clk2}$ + 0.5 * $(s_1 * C_{EQCD} * f_{s1})_{dedicated_Clk}$

+ $(s_2 * C_{EQCI} * f_{s2})_{IO_{CIk}}$]

Where: m = Number of logic modules switching at fm n = Number of input buffers switching at fn p = Number of output buffers switching at f_p q1 = Number of clock loads on the first routed array clock q2 = Number of clock loads on the second routed array clock r_1 = Fixed capacitance due to first routed array clock r₂ = Fixed capacitance due to second routed array clock s₁ = Fixed number of clock loads on the dedicated array clock s2 = Fixed number of clock loads on the dedicated I/O clock C_{FOM} = Equivalent capacitance of logic modules in pF C_{EQI} = Equivalent capacitance of input buffers in pF C_{EOO} = Equivalent capacitance of output buffers in pF C_{EOCR} = Equivalent capacitance of routed array clock in pF C_{EQCD} = Equivalent capacitance of dedicated array clock in pF C_{EOCI} = Equivalent capacitance of dedicated I/O clock in pF C₁ = Output lead capacitance in pF f_m = Average logic module switching rate in MHz fn = Average input buffer switching rate in MHz f_p = Average output buffer switching rate in MHz f_{q1} = Average first routed array clock rate in MHz $f_{\alpha 2}$ = Average second routed array clock rate in MHz f_{s1} = Average dedicated array clock rate in MHz f_{s2} = Average dedicated I/O clock rate in MHz

EQ 5



Table 2-11 • Fixed Capacitance Values for Microsemi FPGAs

| Device Type | r1, routed_Clk1 | r2, routed_Clk2 |
|-------------|-----------------|-----------------|
| A1415A | 60 | 60 |
| A14V15A | 57 | 57 |
| A1425A | 75 | 75 |
| A14V25A | 72 | 72 |
| A1440A | 105 | 105 |
| A14V40A | 100 | 100 |
| A1440B | 105 | 105 |
| A1460A | 165 | 165 |
| A14V60A | 157 | 157 |
| A1460B | 165 | 165 |
| A14100A | 195 | 195 |
| A14V100A | 185 | 185 |
| A14100B | 195 | 195 |

Table 2-12 • Fixed Clock Loads (s1/s2)

| Device Type | s1, Clock Loads on Dedicated Array Clock | s2, Clock Loads on Dedicated I/O Clock |
|-------------|---|---|
| A1415A | 104 | 80 |
| A14V15A | 104 | 80 |
| A1425A | 160 | 100 |
| A14V25A | 160 | 100 |
| A1440A | 288 | 140 |
| A14V40A | 288 | 140 |
| A1440B | 288 | 140 |
| A1460A | 432 | 168 |
| A14V60A | 432 | 168 |
| A1460B | 432 | 168 |
| A14100A | 697 | 228 |
| A14V100A | 697 | 228 |
| A14100B | 697 | 228 |



Determining Average Switching Frequency

To determine the switching frequency for a design, you must have a detailed understanding of the data input values to the circuit. The following guidelines are meant to represent worst-case scenarios so that they can be generally used to predict the upper limits of power dissipation. These guidelines are as follows:

| Table 2-13 • Guidelines | for Pred | licting Powe | Dissipation |
|-------------------------|----------|--------------|-------------|
| | | | Diooipation |

| Data | Value |
|--|---------------------------|
| Logic Modules (m) | 80% of modules |
| Inputs switching (n) | # inputs/4 |
| Outputs switching (p) | # output/4 |
| First routed array clock loads (q1) | 40% of sequential modules |
| Second routed array clock loads (q2) | 40% of sequential modules |
| Load capacitance (CL) | 35 pF |
| Average logic module switching rate (fm) | F/10 |
| Average input switching rate (fn) | F/5 |
| Average output switching rate (fp) | F/10 |
| Average first routed array clock rate (fq1) | F/2 |
| Average second routed array clock rate (fq2) | F/2 |
| Average dedicated array clock rate (fs1) | F |
| Average dedicated I/O clock rate (fs2) | F |



ACT 3 Timing Model



Note: Values shown for A1425A –1 speed grade device.

Figure 2-10 • Timing Model





Figure 2-11 • Output Buffers







Figure 2-13 • Input Buffer Delays





Figure 2-14 • Module Delays



Figure 2-15 • Sequential Module Timing Characteristics









Figure 2-17 • I/O Module: Sequential Output Timing Characteristics



Tightest Delay Distributions

Propagation delay between logic modules depends on the resistive and capacitive loading of the routing tracks, the interconnect elements, and the module inputs being driven. Propagation delay increases as the length of routing tracks, the number of interconnect elements, or the number of inputs increases.

From a design perspective, the propagation delay can be statistically correlated or modeled by the fanout (number of loads) driven by a module. Higher fanout usually requires some paths to have longer lengths of routing track. The ACT 3 family delivers the tightest fanout delay distribution of any FPGA. This tight distribution is achieved in two ways: by decreasing the delay of the interconnect elements and by decreasing the number of interconnect elements per path.

Microsemi's patented PLICE antifuse offers a very low resistive/capacitive interconnect. The ACT 3 family's antifuses, fabricated in 0.8 micron m lithography, offer nominal levels of 200Ω resistance and 6 femtofarad (fF) capacitance per antifuse. The ACT 3 fanout distribution is also tighter than alternative devices due to the low number of antifuses required per interconnect path. The ACT 3 family's proprietary architecture limits the number of antifuses per path to only four, with 90% of interconnects using only two antifuses.

The ACT 3 family's tight fanout delay distribution offers an FPGA design environment in which fanout can be traded for the increased performance of reduced logic level designs. This also simplifies performance estimates when designing with ACT 3 devices.

| Speed Grade | FO = 1 | FO = 2 | FO = 3 | FO = 4 | FO = 8 |
|-------------|--------|--------|--------|--------|--------|
| ACT 3 –3 | 2.9 | 3.2 | 3.4 | 3.7 | 4.8 |
| ACT 3 –2 | 3.3 | 3.7 | 3.9 | 4.2 | 5.5 |
| ACT 3 –1 | 3.7 | 4.2 | 4.4 | 4.8 | 6.2 |
| ACT 3 STD | 4.3 | 4.8 | 5.1 | 5.5 | 7.2 |

Table 2-14 • Logic Module and Routing Delay by Fanout (ns); Worst-Case Commercial Conditions

Notes:

1. Obtained by added $t_{RD(x=FO)}$ to t_{PD} from the Logic Module Timing Characteristics Tables found in this datasheet.

2. The –2 and –3 speed grades have been discontinued. Refer to PDN 0104, PDN 0203, PDN 0604, and PDN 1004 at http://www.microsemi.com/soc/support/notifications/default.aspx#pdn.

Timing Characteristics

Timing characteristics for ACT 3 devices fall into three categories: family dependent, device dependent, and design dependent. The input and output buffer characteristics are common to all ACT 3 family members. Internal routing delays are device dependent. Design dependency means actual delays are not determined until after placement and routing of the user's design is complete. Delay values may then be determined by using the ALS Timer utility or performing simulation with post-layout delays.

Critical Nets and Typical Nets

Propagation delays are expressed only for typical nets, which are used for initial design performance evaluation. Critical net delays can then be applied to the most time-critical paths. Critical nets are determined by net property assignment prior to placement and routing. Up to 6% of the nets in a design may be designated as critical, while 90% of the nets in a design are typical.

Long Tracks

Some nets in the design use long tracks. Long tracks are special routing resources that span multiple rows, columns, or modules. Long tracks employ three and sometimes four antifuse connections. This increases capacitance and resistance, result ng in longer net delays for macros connected to long tracks. Typically up to 6% of nets in a fully utilized device require long tracks. Long tracks contribute approximately 4 ns to 14 ns delay. This additional delay is represented statistically in higher fanout (FO = 8) routing delays in the datasheet specifications section.



Timing Derating

ACT 3 devices are manufactured in a CMOS process. Therefore, device performance varies according to temperature, voltage, and process variations. Minimum timing parameters reflect maximum operating voltage, minimum operating temperature, and best-case processing. Maximum timing parameters reflect minimum operating voltage, maximum operating temperature, and worst-case processing.

Table 2-15 • Timing Derating Factor (Temperature and Voltage)

| (Commercial Minimum/Maximum Specification) x | Indus | strial | Mili | tary |
|--|-------|--------|------|------|
| | Min. | Max. | Min. | Max. |
| | 0.66 | 1.07 | 0.63 | 1.17 |

Table 2-16 • Timing Derating Factor for Designs at Typical Temperature ($T_J = 25^{\circ}C$) and Voltage (5.0 V)

| (Commercial Maximum Specification) x 0.85 | (Commercial Maximum Specification) x | 0.85 |
|---|--------------------------------------|------|
|---|--------------------------------------|------|

Table 2-17 • Temperature and Voltage Derating Factors

(normalized to Worst-Case Commercial, TJ = 4.75 V, 70°C)

| | -55 | -40 | 0 | 25 | 70 | 85 | 125 |
|------|------|------|------|------|------|------|-------|
| 4.50 | 0.72 | 0.76 | 0.85 | 0.90 | 1.04 | 1.07 | 1.117 |
| 4.75 | 0.70 | 0.73 | 0.82 | 0.87 | 1.00 | 1.03 | 1.12 |
| 5.00 | 0.68 | 0.71 | 0.79 | 0.84 | 0.97 | 1.00 | 1.09 |
| 5.25 | 0.66 | 0.69 | 0.77 | 0.82 | 0.94 | 0.97 | 1.06 |
| 5.50 | 0.63 | 0.66 | 0.74 | 0.79 | 0.90 | 0.93 | 1.01 |









A1415A, A14V15A Timing Characteristics

| Table 2-18 • A1415A, A14V15A Worst-Case Commercial Condition | ns. VCC = 4.75 V . T ₁ = 70°C^{1} |
|--|--|
| | |

| Logic N | Iodule Propagation Delays ² | -3 S | peed ³ | –2 S | peed ³ | -1 S | peed | Std. S | Speed | 3.3 V | Speed ¹ | Units | |
|--------------------|--|------|-------------------|------|-------------------|------|------|--------|-------|-------|--------------------|-------|--|
| Parame | eter/Description | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | | |
| t _{PD} | Internal Array Module | | 2.0 | | 2.3 | | 2.6 | | 3.0 | | 3.9 | ns | |
| t _{CO} | Sequential Clock to Q | | 2.0 | | 2.3 | | 2.6 | | 3.0 | | 3.9 | ns | |
| t _{CLR} | Asynchronous Clear to Q | | 2.0 | | 2.3 | | 2.6 | | 3.0 | | 3.9 | ns | |
| Predict | Predicted Routing Delays ⁴ | | | | | | | | | | | | |
| t _{RD1} | FO = 1 Routing Delay | | 0.9 | | 1.0 | | 1.1 | | 1.3 | | 1.7 | ns | |
| t _{RD2} | FO = 2 Routing Delay | | 1.2 | | 1.4 | | 1.6 | | 1.8 | | 2.4 | ns | |
| t _{RD3} | FO = 3 Routing Delay | | 1.4 | | 1.6 | | 1.8 | | 2.1 | | 2.8 | ns | |
| t _{RD4} | FO = 4 Routing Delay | | 1.7 | | 1.9 | | 2.2 | | 2.5 | | 3.3 | ns | |
| t _{RD8} | FO = 8 Routing Delay | | 2.8 | | 3.2 | | 3.6 | | 4.2 | | 5.5 | ns | |
| Logic N | Iodule Sequential Timing | | | | | | | | | | | | |
| t _{SUD} | Flip-Flop Data Input Setup | 0.5 | | 0.6 | | 0.7 | | 0.8 | | 0.8 | | ns | |
| t _{HD} | Flip-Flop Data Input Hold | 0.0 | | 0.0 | | 0.0 | | 0.0 | | 0.0 | | ns | |
| t _{SUD} | Latch Data Input Setup | 0.5 | | 0.6 | | 0.7 | | 0.8 | | 0.8 | | ns | |
| t _{HD} | Latch Data Input Hold | 0.0 | | 0.0 | | 0.0 | | 0.0 | | 0.0 | | ns | |
| t _{WASYN} | Asynchronous Pulse Width | 1.9 | | 2.4 | | 3.2 | | 3.8 | | 4.8 | | ns | |
| t _{WCLKA} | Flip-Flop Clock Pulse Width | 1.9 | | 2.4 | | 3.2 | | 3.8 | | 4.8 | | ns | |
| t _A | Flip-Flop Clock Input Period | 4.0 | | 5.0 | | 6.8 | | 8.0 | | 10.0 | | ns | |
| f _{MAX} | Flip-Flop Clock Frequency | | 250 | | 200 | | 150 | | 125 | | 100 | MHz | |

Notes:

1. VCC = 3.0 V for 3.3 V specifications.

2. For dual-module macros, use $t_{PD} + t_{RD1} + t_{PDn} + t_{CO} + t_{RD1} + t_{PDn}$ or $t_{PD1} + t_{RD1} + t_{SUD}$, whichever is appropriate.

3. The –2 and –3 speed grades have been discontinued. Please refer to the Product Discontinuation Notices (PDNs) listed below:

PDN March 2001 PDN 0104 PDN 0203 PDN 0604 PDN 1004

4. Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual worst-case performance. Post-route timing is based on actual routing delay measurements performed on the device prior to shipment.

A1415A, A14V15A Timing Characteristics (continued)

| Table 2-19 • A1415A. | A14V15A Worst-Case | Commercial Conditions | , VCC = 4.75 V, T _J = 70°C |
|----------------------|---|------------------------------|---------------------------------------|
| | ,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,, | | , |

| I/O Moo | dule Input Propagation Delays | -3 Sp | beed ¹ | -2 Sp | beed ¹ | –1 S | peed | Std. | Speed | 3.3 V Speed ² | | Units |
|--------------------|--------------------------------------|-------|-------------------|-------|-------------------|------|------|------|-------|--------------------------|------|-------|
| Parame | eter/Description | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | Í |
| t _{INY} | Input Data Pad to Y | | 2.8 | | 3.2 | | 3.6 | | 4.2 | | 5.5 | ns |
| t _{ICKY} | Input Reg IOCLK Pad to Y | | 4.7 | | 5.3 | | 6.0 | | 7.0 | | 9.2 | ns |
| t _{OCKY} | Output Reg IOCLK Pad to Y | | 4.7 | | 5.3 | | 6.0 | | 7.0 | | 9.2 | ns |
| t _{ICLRY} | Input Asynchronous Clear to Y | | 4.7 | | 5.3 | | 6.0 | | 7.0 | | 9.2 | ns |
| t _{OCLRY} | Output Asynchronous Clear to Y | | 4.7 | | 5.3 | | 6.0 | | 7.0 | | 9.2 | ns |
| Predict | ed Input Routing Delays ² | | | | | | | | | | | |
| t _{RD1} | FO = 1 Routing Delay | | 0.9 | | 1.0 | | 1.1 | | 1.3 | | 1.7 | ns |
| t _{RD2} | FO = 2 Routing Delay | | 1.2 | | 1.4 | | 1.6 | | 1.8 | | 2.4 | ns |
| t _{RD3} | FO = 3 Routing Delay | | 1.4 | | 1.6 | | 1.8 | | 2.1 | | 2.8 | ns |
| t _{RD4} | FO = 4 Routing Delay | | 1.7 | | 1.9 | | 2.2 | | 2.5 | | 3.3 | ns |
| t _{RD8} | FO = 8 Routing Delay | | 2.8 | | 3.2 | | 3.6 | | 4.2 | | 5.5 | ns |
| I/O Moo | dule Sequential Timing (wrt IOCLK | pad) | | | | | | | | | | |
| t _{INH} | Input F-F Data Hold | 0.0 | | 0.0 | | 0.0 | | 0.0 | | 0.0 | | ns |
| t _{INSU} | Input F-F Data Setup | 2.0 | | 2.3 | | 2.5 | | 3.0 | | 3.0 | | ns |
| t _{IDEH} | Input Data Enable Hold | 0.0 | | 0.0 | | 0.0 | | 0.0 | | 0.0 | | ns |
| t _{IDESU} | Input Data Enable Setup | 5.8 | | 6.5 | | 7.5 | | 8.6 | | 8.6 | | ns |
| t _{OUTH} | Output F-F Data hold | 0.7 | | 0.8 | | 0.9 | | 1.0 | | 1.0 | | ns |
| t _{OUTSU} | Output F-F Data Setup | 0.7 | | 0.8 | | 0.9 | | 1.0 | | 1.0 | | ns |
| t _{ODEH} | Output Data Enable Hold | 0.3 | | 0.4 | | 0.4 | | 0.5 | | 0.5 | | ns |
| f _{ODESU} | Output Data Enable Setup | 1.3 | | 1.5 | | 1.7 | | 2.0 | | 2.0 | | ns |

Notes:

1. The –2 and –3 speed grades have been discontinued. Please refer to the Product Discontinuation Notices (PDNs) listed below:

PDN March 2001 PDN 0104 PDN 0203 PDN 0604 PDN 1004

 Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual worst-case performance. Post-route timing is based on actual routing delay measurements performed on the device prior to shipment.



A1415A, A14V15A Timing Characteristics (continued)

Table 2-20 • A1415A, A14V15A Worst-Case Commercial Conditions, VCC = 4.75 V, T_J = 70°C

| | | -2.01 | beed ² | -2 SI | peed- | -1 S | peed | Std. | Std. Speed 3.3 V S | | | Units |
|--------------------|--|-------|-------------------|-------|-------|------|------|------|--------------------|------|------|-------|
| Parame | ter/Description | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | |
| t _{DHS} | Data to Pad, High Slew | | 5.0 | | 5.6 | | 6.4 | | 7.5 | | 9.8 | ns |
| t _{DLS} | Data to Pad, Low Slew | | 8.0 | | 9.0 | | 10.2 | | 12.0 | | 15.6 | ns |
| t _{ENZHS} | Enable to Pad, Z to H/L, High Slew | | 4.0 | | 4.5 | | 5.1 | | 6.0 | | 7.8 | ns |
| t _{ENZLS} | Enable to Pad, Z to H/L, Low Slew | | 7.4 | | 8.3 | | 9.4 | | 11.0 | | 14.3 | ns |
| t _{ENHSZ} | Enable to Pad, H/L to Z, High Slew | | 6.5 | | 7.5 | | 8.5 | | 10.0 | | 13.0 | ns |
| t _{ENLSZ} | Enable to Pad, H/L to Z, Low Slew | | 6.5 | | 7.5 | | 8.5 | | 10.0 | | 13.0 | ns |
| t _{CKHS} | IOCLK Pad to Pad H/L, High Slew | | 7.5 | | 7.5 | | 9.0 | | 10.0 | | 13.0 | ns |
| t _{CKLS} | IOCLK Pad to Pad H/L, Low Slew | | 11.3 | | 11.3 | | 13.5 | | 15.0 | | 19.5 | ns |
| d _{TLHHS} | Delta Low to High, High Slew | | 0.02 | | 0.02 | | 0.03 | | 0.03 | | 0.04 | ns/pF |
| d _{TLHLS} | Delta Low to High, Low Slew | | 0.05 | | 0.05 | | 0.06 | | 0.07 | | 0.09 | ns/pF |
| d _{THLHS} | Delta High to Low, High Slew | | 0.04 | | 0.04 | | 0.04 | | 0.05 | | 0.07 | ns/pF |
| d _{THLLS} | Delta High to Low, Low Slew | | 0.05 | | 0.05 | | 0.06 | | 0.07 | | 0.09 | ns/pF |
| I/O Mod | lule – CMOS Output Timing ¹ | | | | | | | | | | | |
| t _{DHS} | Data to Pad, High Slew | | 6.2 | | 7.0 | | 7.9 | | 9.3 | | 12.1 | ns |
| t _{DLS} | Data to Pad, Low Slew | | 11.7 | | 13.1 | | 14.9 | | 17.5 | | 22.8 | ns |
| t _{ENZHS} | Enable to Pad, Z to H/L, High Slew | | 5.2 | | 5.9 | | 6.6 | | 7.8 | | 10.1 | ns |
| t _{ENZLS} | Enable to Pad, Z to H/L, Low Slew | | 8.9 | | 10.0 | | 11.3 | | 13.3 | | 17.3 | ns |
| t _{ENHSZ} | Enable to Pad, H/L to Z, High Slew | | 6.7 | | 7.5 | | 8.5 | | 10.0 | | 13.0 | ns |
| t _{ENLSZ} | Enable to Pad, H/L to Z, Low Slew | | 6.7 | | 7.5 | | 9.0 | | 10.0 | | 13.0 | ns |
| t _{CKHS} | IOCLK Pad to Pad H/L, High Slew | | 8.9 | | 8.9 | | 10.7 | | 11.8 | | 15.3 | ns |
| t _{CKLS} | IOCLK Pad to Pad H/L, Low Slew | | 13.0 | | 13.0 | | 15.6 | | 17.3 | | 22.5 | ns |
| d _{TLHHS} | Delta Low to High, High Slew | | 0.04 | | 0.04 | | 0.05 | | 0.06 | | 0.08 | ns/pF |
| d _{TLHLS} | Delta Low to High, Low Slew | | 0.07 | | 0.08 | | 0.09 | | 0.11 | | 0.14 | ns/pF |
| d _{THLHS} | Delta High to Low, High Slew | | 0.03 | | 0.03 | | 0.03 | | 0.04 | | 0.05 | ns/pF |
| d _{THLLS} | Delta High to Low, Low Slew | | 0.04 | | 0.04 | | 0.04 | | 0.05 | | 0.07 | ns/pF |

Notes:

1. Delays based on 35 pF loading.

2. The –2 and –3 speed grades have been discontinued. Please refer to the Product Discontinuation Notices (PDNs) listed below:

PDN March 2001 PDN 0104 PDN 0203 PDN 0604 PDN 1004

A1415A, A14V15A Timing Characteristics (continued)

Table 2-21 • A1415A, A14V15A Worst-Case Commercial Conditions, VCC = 4.75 V, $T_J = 70^{\circ}C$

| Dedicate | d (hardwired) I/O Clock Network | –3 S | peed | –2 S | peed | –1 S | peed | Std. | Speed | Speed 3.3 V Speed ¹ | | |
|----------------------|---|------|------|------|------|------|------|------|-------|--------------------------------|------------|-----|
| Paramete | er/Description | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | |
| t _{IOCKH} | Input Low to High (pad to I/O module input) | | 2.0 | | 2.3 | | 2.6 | | 3.0 | | 3.5 | ns |
| t _{IOPWH} | Minimum Pulse Width High | 1.9 | | 2.4 | | 3.3 | | 3.8 | | 4.8 | | ns |
| t _{IPOWL} | Minimum Pulse Width Low | 1.9 | | 2.4 | | 3.3 | | 3.8 | | 4.8 | | ns |
| t _{IOSAPW} | Minimum Asynchronous Pulse Width | 1.9 | | 2.4 | | 3.3 | | 3.8 | | 4.8 | | ns |
| t _{IOCKSW} | Maximum Skew | | 0.4 | | 0.4 | | 0.4 | | 0.4 | | 0.4 | ns |
| t _{IOP} | Minimum Period | 4.0 | | 5.0 | | 6.8 | | 8.0 | | 10.0 | | ns |
| f _{IOMAX} | Maximum Frequency | | 250 | | 200 | | 150 | | 125 | | 100 | MHz |
| Dedicate | d (hardwired) Array Clock | | | | | | | | | | | |
| ^t нскн | Input Low to High (pad to S-module input) | | 3.0 | | 3.4 | | 3.9 | | 4.5 | | 5.5 | ns |
| t _{HCKL} | Input High to Low (pad to S-module input) | | 3.0 | | 3.4 | | 3.9 | | 4.5 | | 5.5 | ns |
| t _{HPWH} | Minimum Pulse Width High | 1.9 | | 2.4 | | 3.3 | | 3.8 | | 4.8 | | ns |
| t _{HPWL} | Minimum Pulse Width Low | 1.9 | | 2.4 | | 3.3 | | 3.8 | | 4.8 | | ns |
| t _{HCKSW} | Delta High to Low, Low Slew | | 0.3 | | 0.3 | | 0.3 | | 0.3 | | 0.3 | ns |
| t _{HP} | Minimum Period | 4.0 | | 5.0 | | 6.8 | | 8.0 | | 10.0 | | ns |
| f _{HMAX} | Maximum Frequency | | 250 | | 200 | | 150 | | 125 | | 100 | MHz |
| Routed A | rray Clock Networks | | | • | • | | | | - | | | |
| t _{RCKH} | Input Low to High (FO = 64) | | 3.7 | | 4.1 | | 4.7 | | 5.5 | | 9.0 | ns |
| t _{RCKL} | Input High to Low (FO = 64) | | 4.0 | | 4.5 | | 5.1 | | 6.0 | | 9.0 | ns |
| t _{RPWH} | Min. Pulse Width High (FO = 64) | 3.3 | | 3.8 | | 4.2 | | 4.9 | | 6.5 | | ns |
| t _{RPWL} | Min. Pulse Width Low (FO = 64) | 3.3 | | 3.8 | | 4.2 | | 4.9 | | 6.5 | | ns |
| t _{RCKSW} | Maximum Skew (FO = 128) | | 0.7 | | 0.8 | | 0.9 | | 1.0 | | 1.0 | ns |
| t _{RP} | Minimum Period (FO = 64) | 6.8 | | 8.0 | | 8.7 | | 10.0 | | 13.4 | | ns |
| f _{RMAX} | Maximum Frequency (FO = 64) | | 150 | | 125 | | 115 | | 100 | | 75 | MHz |
| Clock-to- | Clock Skews | | | • | • | | | | - | | | |
| t _{IOHCKSW} | I/O Clock to H-Clock Skew | 0.0 | 1.7 | 0.0 | 1.8 | 0.0 | 2.0 | 0.0 | 2.2 | 0.0 | 3.0 | ns |
| t _{IORCKSW} | I/O Clock to R-Clock Skew (FO = 64) | 0.0 | 1.0 | 0.0 | 1.0 | 0.0 | 1.0 | 0.0 | 1.0 | 0.0 | 3.0 | ns |
| t _{HRCKSW} | H-Clock to R-Clock Skew (FO = 64) (FO = 50% maximum) | 0.0 | 1.0 | 0.0 | 1.0 | 0.0 | 1.0 | 0.0 | 1.0 | 0.0 0.0 | 3.0 3.0 | ns |

Notes:

1. Delays based on 35 pF loading.

2. The –2 and –3 speed grades have been discontinued. Refer to PDN 0104, PDN 0203, PDN 0604, and PDN 1004 at http://www.microsemi.com/soc/support/notifications/default.aspx#pdn.



A1425A, A14V25A Timing Characteristics

| Table 2-22 • A1425A | A14V25A Worst-Cas | se Commercial Co | onditions V | VCC = 4.75 V | $T_{1} = 70^{\circ}C^{1}$ |
|---------------------|--------------------|------------------|-------------|--------------|---------------------------|
| | , AITTLOA MOISLOUS | | onunons, | 100 = 1.10 | 1 - 10 0 |

| Logic Module Propagation Delays ² | | -3 Speed ³ | | –2 Speed ³ | | -1 Speed | | Std. Speed | | 3.3 V Speed ¹ | | Units |
|--|---------------------------------------|-----------------------|------|-----------------------|------|----------|------|------------|------|--------------------------|------|-------|
| Parameter/Description | | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | |
| t _{PD} | Internal Array Module | | 2.0 | | 2.3 | | 2.6 | | 3.0 | | 3.9 | ns |
| t _{CO} | Sequential Clock to Q | | 2.0 | | 2.3 | | 2.6 | | 3.0 | | 3.9 | ns |
| t _{CLR} | Asynchronous Clear to Q | | 2.0 | | 2.3 | | 2.6 | | 3.0 | | 3.9 | ns |
| Predict | Predicted Routing Delays ⁴ | | | | | | | | | | | |
| t _{RD1} | FO = 1 Routing Delay | | 0.9 | | 1.0 | | 1.1 | | 1.3 | | 1.7 | ns |
| t _{RD2} | FO = 2 Routing Delay | | 1.2 | | 1.4 | | 1.6 | | 1.8 | | 2.4 | ns |
| t _{RD3} | FO = 3 Routing Delay | | 1.4 | | 1.6 | | 1.8 | | 2.1 | | 2.8 | ns |
| t _{RD4} | FO = 4 Routing Delay | | 1.7 | | 1.9 | | 2.2 | | 2.5 | | 3.3 | ns |
| t _{RD8} | FO = 8 Routing Delay | | 2.8 | | 3.2 | | 3.6 | | 4.2 | | 5.5 | ns |
| Logic N | Iodule Sequential Timing | | | | | | | | | | | |
| t _{SUD} | Flip-Flop Data Input Setup | 0.5 | | 0.6 | | 0.7 | | 0.8 | | 0.8 | | ns |
| t _{HD} | Flip-Flop Data Input Hold | 0.0 | | 0.0 | | 0.0 | | 0.0 | | 0.0 | | ns |
| t _{SUD} | Latch Data Input Setup | 0.5 | | 0.6 | | 0.7 | | 0.8 | | 0.8 | | ns |
| t _{HD} | Latch Data Input Hold | 0.0 | | 0.0 | | 0.0 | | 0.0 | | 0.0 | | ns |
| t _{WASYN} | Asynchronous Pulse Width | 1.9 | | 2.4 | | 3.2 | | 3.8 | | 4.8 | | ns |
| t _{WCLKA} | Flip-Flop Clock Pulse Width | 1.9 | | 2.4 | | 3.2 | | 3.8 | | 4.8 | | ns |
| t _A | Flip-Flop Clock Input Period | 4.0 | | 5.0 | | 6.8 | | 8.0 | | 10.0 | | ns |
| f _{MAX} | Flip-Flop Clock Frequency | | 250 | | 200 | | 150 | | 125 | | 100 | MHz |

Notes:

1. VCC = 3.0 V for 3.3 V specifications.

2. For dual-module macros, use $t_{PD} + t_{RD1} + t_{PDn} + t_{CO} + t_{RD1} + t_{PDn}$ or $t_{PD1} + t_{RD1} + t_{SUD}$, whichever is appropriate.

3. The –2 and –3 speed grades have been discontinued. Refer to PDN 0104, PDN 0203, PDN 0604, and PDN 1004 at http://www.microsemi.com/soc/support/notifications/default.aspx#pdn.

4. Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual worst-case performance. Post-route timing is based on actual routing delay measurements performed on the device prior to shipment.

A1425A, A14V25A Timing Characteristics (continued)

| I/O Module Input Propagation Delays | | -3 Speed ¹ -2 S | | -2 Sp | peed ¹ –1 S | | peed Std. | | Speed | 3.3 V Speed ¹ | | Units |
|-------------------------------------|--------------------------------------|----------------------------|------|-------|------------------------|------|-----------|------|-------|--------------------------|------|-------|
| Parameter/Description | | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | |
| t _{INY} | Input Data Pad to Y | | 2.8 | | 3.2 | | 3.6 | | 4.2 | | 5.5 | ns |
| t _{ICKY} | Input Reg IOCLK Pad to Y | | 4.7 | | 5.3 | | 6.0 | | 7.0 | | 9.2 | ns |
| t _{OCKY} | Output Reg IOCLK Pad to Y | | 4.7 | | 5.3 | | 6.0 | | 7.0 | | 9.2 | ns |
| t _{ICLRY} | Input Asynchronous Clear to Y | | 4.7 | | 5.3 | | 6.0 | | 7.0 | | 9.2 | ns |
| t _{OCLRY} | Output Asynchronous Clear to Y | | 4.7 | | 5.3 | | 6.0 | | 7.0 | | 9.2 | ns |
| Predict | ed Input Routing Delays ² | | | | | | | | | | | |
| t _{RD1} | FO = 1 Routing Delay | | 0.9 | | 1.0 | | 1.1 | | 1.3 | | 1.7 | ns |
| t _{RD2} | FO = 2 Routing Delay | | 1.2 | | 1.4 | | 1.6 | | 1.8 | | 2.4 | ns |
| t _{RD3} | FO = 3 Routing Delay | | 1.4 | | 1.6 | | 1.8 | | 2.1 | | 2.8 | ns |
| t _{RD4} | FO = 4 Routing Delay | | 1.7 | | 1.9 | | 2.2 | | 2.5 | | 3.3 | ns |
| t _{RD8} | FO = 8 Routing Delay | | 2.8 | | 3.2 | | 3.6 | | 4.2 | | 5.5 | ns |
| I/O Mod | dule Sequential Timing (wrt IOCLK | pad) | | | • | | • | | | | | |
| t _{INH} | Input F-F Data Hold | 0.0 | | 0.0 | | 0.0 | | 0.0 | | 0.0 | | ns |
| t _{INSU} | Input F-F Data Setup | 1.8 | | 2.0 | | 2.3 | | 2.7 | | 3.0 | | ns |
| t _{IDEH} | Input Data Enable Hold | 0.0 | | 0.0 | | 0.0 | | 0.0 | | 0.0 | | ns |
| t _{IDESU} | Input Data Enable Setup | 5.8 | | 6.5 | | 7.5 | | 8.6 | | 8.6 | | ns |
| t _{OUTH} | Output F-F Data hold | 0.7 | | 0.8 | | 0.9 | | 1.0 | | 1.0 | | ns |
| t _{OUTSU} | Output F-F Data Setup | 0.7 | | 0.8 | | 0.9 | | 1.0 | | 1.0 | | ns |
| t _{ODEH} | Output Data Enable Hold | 0.3 | | 0.4 | | 0.4 | | 0.5 | | 0.5 | | ns |
| f _{ODESU} | Output Data Enable Setup | 1.3 | | 1.5 | | 1.7 | | 2.0 | | 2.0 | | ns |

Notes: *

1. The –2 and –3 speed grades have been discontinued. Refer to PDN 0104, PDN 0203, PDN 0604, and PDN 1004 at http://www.microsemi.com/soc/support/notifications/default.aspx#pdn.

 Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual worst-case performance. Post-route timing is based on actual routing delay measurements performed on the device prior to shipment.



A1425A, A14V25A Timing Characteristics (continued)

Table 2-24 • A1425A, A14V25A Worst-Case Commercial Conditions, VCC = 4.75 V, T_J = 70°C

| | | -3 Speed ² -2 Speed ² | | | –1 S | peed | Std. | Std. Speed | | 3.3 V Speed ¹ | | |
|--------------------|--|---|------|------|------|------|------|------------|------|--------------------------|------|-------|
| | | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | |
| t _{DHS} | Data to Pad, High Slew | | 5.0 | | 5.6 | | 6.4 | | 7.5 | | 9.8 | ns |
| t _{DLS} | Data to Pad, Low Slew | | 8.0 | | 9.0 | | 10.2 | | 12.0 | | 15.6 | ns |
| t _{ENZHS} | Enable to Pad, Z to H/L, High Slew | | 4.0 | | 4.5 | | 5.1 | | 6.0 | | 7.8 | ns |
| t _{ENZLS} | Enable to Pad, Z to H/L, Low Slew | | 7.4 | | 8.3 | | 9.4 | | 11.0 | | 14.3 | ns |
| t _{ENHSZ} | Enable to Pad, H/L to Z, High Slew | | 6.5 | | 7.5 | | 8.5 | | 10.0 | | 13.0 | ns |
| t _{ENLSZ} | Enable to Pad, H/L to Z, Low Slew | | 6.5 | | 7.5 | | 8.5 | | 10.0 | | 13.0 | ns |
| t _{CKHS} | IOCLK Pad to Pad H/L, High Slew | | 7.5 | | 7.5 | | 9.0 | | 10.0 | | 13.0 | ns |
| t _{CKLS} | IOCLK Pad to Pad H/L, Low Slew | | 11.3 | | 11.3 | | 13.5 | | 15.0 | | 19.5 | ns |
| d _{TLHHS} | Delta Low to High, High Slew | | 0.02 | | 0.02 | | 0.03 | | 0.03 | | 0.04 | ns/pF |
| d _{TLHLS} | Delta Low to High, Low Slew | | 0.05 | | 0.05 | | 0.06 | | 0.07 | | 0.09 | ns/pF |
| d _{THLHS} | Delta High to Low, High Slew | | 0.04 | | 0.04 | | 0.04 | | 0.05 | | 0.07 | ns/pF |
| d _{THLLS} | Delta High to Low, Low Slew | | 0.05 | | 0.05 | | 0.06 | | 0.07 | | 0.09 | ns/pF |
| I/O Moc | dule – CMOS Output Timing ¹ | | | • | | | | | | | | |
| t _{DHS} | Data to Pad, High Slew | | 6.2 | | 7.0 | | 7.9 | | 9.3 | | 12.1 | ns |
| t _{DLS} | Data to Pad, Low Slew | | 11.7 | | 13.1 | | 14.9 | | 17.5 | | 22.8 | ns |
| t _{ENZHS} | Enable to Pad, Z to H/L, High Slew | | 5.2 | | 5.9 | | 6.6 | | 7.8 | | 10.1 | ns |
| t _{ENZLS} | Enable to Pad, Z to H/L, Low Slew | | 8.9 | | 10.0 | | 11.3 | | 13.3 | | 17.3 | ns |
| t _{ENHSZ} | Enable to Pad, H/L to Z, High Slew | | 6.7 | | 7.5 | | 8.5 | | 10.0 | | 13.0 | ns |
| t _{ENLSZ} | Enable to Pad, H/L to Z, Low Slew | | 6.7 | | 7.5 | | 9.0 | | 10.0 | | 13.0 | ns |
| t _{CKHS} | IOCLK Pad to Pad H/L, High Slew | | 8.9 | | 8.9 | | 10.7 | | 11.8 | | 15.3 | ns |
| t _{CKLS} | IOCLK Pad to Pad H/L, Low Slew | | 13.0 | | 13.0 | | 15.6 | | 17.3 | | 22.5 | ns |
| d _{TLHHS} | Delta Low to High, High Slew | | 0.04 | | 0.04 | | 0.05 | | 0.06 | | 0.08 | ns/pF |
| d _{TLHLS} | Delta Low to High, Low Slew | | 0.07 | | 0.08 | | 0.09 | | 0.11 | | 0.14 | ns/pF |
| d _{THLHS} | Delta High to Low, High Slew | | 0.03 | | 0.03 | | 0.03 | | 0.04 | | 0.05 | ns/pF |
| d _{THLLS} | Delta High to Low, Low Slew | | 0.04 | | 0.04 | | 0.04 | | 0.05 | | 0.07 | ns/pF |

Notes: *

1. Delays based on 35 pF loading.

2. The –2 and –3 speed grades have been discontinued. Refer to PDN 0104, PDN 0203, PDN 0604, and PDN 1004 at http://www.microsemi.com/soc/support/notifications/default.aspx#pdn.
A1425A, A14V25A Timing Characteristics (continued)

Table 2-25 • A1425A, A14V25A Worst-Case Commercial Conditions, VCC = 4.75 V, T_J = 70°C

| Dedicate | d (hardwired) I/O Clock Network | —3 Sp | beed ¹ | -2 Sp | beed ¹ | –1 S | peed | Std. | Speed | I 3.3 V Speed ¹ | | Units |
|----------------------|--|------------|-------------------|------------|-------------------|------------|------------|------------|------------|----------------------------|------------|-------|
| Paramete | er/Description | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | |
| t _{IOCKH} | Input Low to High (pad to I/O module input) | | 2.0 | | 2.3 | | 2.6 | | 3.0 | | 3.5 | ns |
| t _{IOPWH} | Minimum Pulse Width High | 1.9 | | 2.4 | | 3.3 | | 3.8 | | 4.8 | | ns |
| t _{IPOWL} | Minimum Pulse Width Low | 1.9 | | 2.4 | | 3.3 | | 3.8 | | 4.8 | | ns |
| t _{IOSAPW} | Minimum Asynchronous Pulse Width | 1.9 | | 2.4 | | 3.3 | | 3.8 | | 4.8 | | ns |
| t _{IOCKSW} | Maximum Skew | | 0.4 | | 0.4 | | 0.4 | | 0.4 | | 0.4 | ns |
| t _{IOP} | Minimum Period | 4.0 | | 5.0 | | 6.8 | | 8.0 | | 10.0 | | ns |
| f _{IOMAX} | Maximum Frequency | | 250 | | 200 | | 150 | | 125 | | 100 | MHz |
| Dedicate | d (hardwired) Array Clock | | | | | | | | | | | |
| t _{HCKH} | Input Low to High (pad to S-module input) | | 3.0 | | 3.4 | | 3.9 | | 4.5 | | 5.5 | ns |
| t _{HCKL} | Input High to Low (pad to S-module input) | | 3.0 | | 3.4 | | 3.9 | | 4.5 | | 5.5 | ns |
| t _{HPWH} | Minimum Pulse Width High | 1.9 | | 2.4 | | 3.3 | | 3.8 | | 4.8 | | ns |
| t _{HPWL} | Minimum Pulse Width Low | 1.9 | | 2.4 | | 3.3 | | 3.8 | | 4.8 | | ns |
| t _{HCKSW} | Delta High to Low, Low Slew | | 0.3 | | 0.3 | | 0.3 | | 0.3 | | 0.3 | ns |
| t _{HP} | Minimum Period | 4.0 | | 5.0 | | 6.8 | | 8.0 | | 10.0 | | ns |
| f _{HMAX} | Maximum Frequency | | 250 | | 200 | | 150 | | 125 | | 100 | MHz |
| Routed A | nray Clock Networks | | | | | - | | | | | | |
| t _{RCKH} | Input Low to High (FO = 64) | | 3.7 | | 4.1 | | 4.7 | | 5.5 | | 9.0 | ns |
| t _{RCKL} | Input High to Low (FO = 64) | | 4.0 | | 4.5 | | 5.1 | | 6.0 | | 9.0 | ns |
| t _{RPWH} | Min. Pulse Width High (FO = 64) | 3.3 | | 3.8 | | 4.2 | | 4.9 | | 6.5 | | ns |
| t _{RPWL} | Min. Pulse Width Low (FO = 64) | 3.3 | | 3.8 | | 4.2 | | 4.9 | | 6.5 | | ns |
| t _{RCKSW} | Maximum Skew (FO = 128) | | 0.7 | | 0.8 | | 0.9 | | 1.0 | | 1.0 | ns |
| t _{RP} | Minimum Period (FO = 64) | 6.8 | | 8.0 | | 8.7 | | 10.0 | | 13.4 | | ns |
| f _{RMAX} | Maximum Frequency (FO = 64) | | 150 | | 125 | | 115 | | 100 | | 75 | MHz |
| Clock-to- | Clock Skews | | | | | | | | | | | |
| t _{IOHCKSW} | I/O Clock to H-Clock Skew | 0.0 | 1.7 | 0.0 | 1.8 | 0.0 | 2.0 | 0.0 | 2.2 | 0.0 | 3.0 | ns |
| t _{IORCKSW} | I/O Clock to R-Clock Skew (FO = 64) (FO = 80) | 0.0 0.0 | 1.0 3.0 | 0.0 0.0 | 1.0 3.0 | 0.0 0.0 | 1.0 3.0 | 0.0 0.0 | 1.0 3.0 | 0.0 0.0 | 3.0 3.0 | ns |
| t _{HRCKSW} | H-Clock to R-Clock Skew (FO = 64) (FO = 80) | 0.0 0.0 | 1.0 3.0 | 0.0 0.0 | 1.0 3.0 | 0.0 0.0 | 1.0 3.0 | 0.0 0.0 | 1.0 3.0 | 0.0 0.0 | 1.0 3.0 | ns |

Notes:

1. The -2 and -3 speed grades have been discontinued. Refer to PDN 0104, PDN 0203, PDN 0604, and PDN 1004 at http://www.microsemi.com/soc/support/notifications/default.aspx#pdn.

2. Delays based on 35 pF loading.



A1440A, A14V40A Timing Characteristics

| Table 2-26 • A1440A | A14V40A Worst-Case C | ommercial Conditions. | $VCC = 4.75 V, T_{J} = 70^{\circ}C^{1}$ |
|---------------------|----------------------|-----------------------|---|
| | | | |

| Logic N | Iodule Propagation Delays ² | -3 S | oeed ³ | –2 S | beed ³ | -1 S | peed | Std. Speed | | 3.3 V Speed ¹ | | Units |
|--------------------|--|------|-------------------|------|-------------------|------|------|------------|------|--------------------------|------|-------|
| Parame | eter/Description | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | 1 |
| t _{PD} | Internal Array Module | | 2.0 | | 2.3 | | 2.6 | | 3.0 | | 3.9 | ns |
| t _{CO} | Sequential Clock to Q | | 2.0 | | 2.3 | | 2.6 | | 3.0 | | 3.9 | ns |
| t _{CLR} | Asynchronous Clear to Q | | 2.0 | | 2.3 | | 2.6 | | 3.0 | | 3.9 | ns |
| Predict | ed Routing Delays ⁴ | | | | | | | | | | | |
| t _{RD1} | FO = 1 Routing Delay | | 0.9 | | 1.0 | | 1.1 | | 1.3 | | 1.7 | ns |
| t _{RD2} | FO = 2 Routing Delay | | 1.2 | | 1.4 | | 1.6 | | 1.8 | | 2.4 | ns |
| t _{RD3} | FO = 3 Routing Delay | | 1.4 | | 1.6 | | 1.8 | | 2.1 | | 2.8 | ns |
| t _{RD4} | FO = 4 Routing Delay | | 1.7 | | 1.9 | | 2.2 | | 2.5 | | 3.3 | ns |
| t _{RD8} | FO = 8 Routing Delay | | 2.8 | | 3.2 | | 3.6 | | 4.2 | | 5.5 | ns |
| Logic N | Nodule Sequential Timing | | | | | | | | | | | |
| t _{SUD} | Flip-Flop Data Input Setup | 0.5 | | 0.6 | | 0.7 | | 0.8 | | 0.8 | | ns |
| t _{HD} | Flip-Flop Data Input Hold | 0.0 | | 0.0 | | 0.0 | | 0.0 | | 0.0 | | ns |
| t _{SUD} | Latch Data Input Setup | 0.5 | | 0.6 | | 0.7 | | 0.8 | | 0.8 | | ns |
| t _{HD} | Latch Data Input Hold | 0.0 | | 0.0 | | 0.0 | | 0.0 | | 0.0 | | ns |
| t _{WASYN} | Asynchronous Pulse Width | 1.9 | | 2.4 | | 3.2 | | 3.8 | | 4.8 | | ns |
| t _{WCLKA} | Flip-Flop Clock Pulse Width | 1.9 | | 2.4 | | 3.2 | | 3.8 | | 4.8 | | ns |
| t _A | Flip-Flop Clock Input Period | 4.0 | | 5.0 | | 6.8 | | 8.0 | | 10.0 | | ns |
| f _{MAX} | Flip-Flop Clock Frequency | | 250 | | 200 | | 150 | | 125 | | 100 | MHz |

Notes:

1. VCC = 3.0 V for 3.3 V specifications.

2. For dual-module macros, use $t_{PD} + t_{RD1} + t_{PDn} + t_{CO} + t_{RD1} + t_{PDn}$ or $t_{PD1} + t_{RD1} + t_{SUD}$, whichever is appropriate.

3. The -2 and -3 speed grades have been discontinued. Refer to PDN 0104, PDN 0203, PDN 0604, and PDN 1004 at http://www.microsemi.com/soc/support/notifications/default.aspx#pdn.

4. Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual worst-case performance. Post-route timing is based on actual routing delay measurements performed on the device prior to shipment.

A1440A, A14V40A Timing Characteristics (continued)

| Table 2-27 • A1440A | A14V40A Worst-Case (| Commercial Conditions | VCC = 4.75 V, T _J = 70°C |
|------------------------|----------------------|-----------------------|-------------------------------------|
| 1 able 2-27 • A 1440A, | A 14V4UA WUISI-Case | | $v_{\rm CC} = 4.75 v, 1j = 70 C$ |

| I/O Moc | dule Input Propagation Delays | -3 S | beed ¹ | -2 Sp | beed ¹ | –1 S | peed | Std. | Std. Speed | | 3.3 V Speed ¹ | |
|--------------------|--------------------------------------|------|-------------------|-------|-------------------|------|------|------|------------|------|--------------------------|----|
| Parame | eter/Description | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | |
| t _{INY} | Input Data Pad to Y | | 2.8 | | 3.2 | | 3.6 | | 4.2 | | 5.5 | ns |
| t _{ICKY} | Input Reg IOCLK Pad to Y | | 4.7 | | 5.3 | | 6.0 | | 7.0 | | 9.2 | ns |
| t _{OCKY} | Output Reg IOCLK Pad to Y | | 4.7 | | 5.3 | | 6.0 | | 7.0 | | 9.2 | ns |
| t _{ICLRY} | Input Asynchronous Clear to Y | | 4.7 | | 5.3 | | 6.0 | | 7.0 | | 9.2 | ns |
| t _{OCLRY} | Output Asynchronous Clear to Y | | 4.7 | | 5.3 | | 6.0 | | 7.0 | | 9.2 | ns |
| Predict | ed Input Routing Delays ² | | | | | | | | | | | |
| t _{RD1} | FO = 1 Routing Delay | | 0.9 | | 1.0 | | 1.1 | | 1.3 | | 1.7 | ns |
| t _{RD2} | FO = 2 Routing Delay | | 1.2 | | 1.4 | | 1.6 | | 1.8 | | 2.4 | ns |
| t _{RD3} | FO = 3 Routing Delay | | 1.4 | | 1.6 | | 1.8 | | 2.1 | | 2.8 | ns |
| t _{RD4} | FO = 4 Routing Delay | | 1.7 | | 1.9 | | 2.2 | | 2.5 | | 3.3 | ns |
| t _{RD8} | FO = 8 Routing Delay | | 2.8 | | 3.2 | | 3.6 | | 4.2 | | 5.5 | ns |
| I/O Moc | dule Sequential Timing (wrt IOCLK | pad) | | | | | | | | | | |
| t _{INH} | Input F-F Data Hold | 0.0 | | 0.0 | | 0.0 | | 0.0 | | 0.0 | | ns |
| t _{INSU} | Input F-F Data Setup | 1.8 | | 1.7 | | 2.0 | | 2.3 | | 2.3 | | ns |
| t _{IDEH} | Input Data Enable Hold | 0.0 | | 0.0 | | 0.0 | | 0.0 | | 0.0 | | ns |
| t _{IDESU} | Input Data Enable Setup | 5.8 | | 6.5 | | 7.5 | | 8.6 | | 8.6 | | ns |
| t _{OUTH} | Output F-F Data hold | 0.7 | | 0.8 | | 0.9 | | 1.0 | | 1.0 | | ns |
| t _{OUTSU} | Output F-F Data Setup | 0.7 | | 0.8 | | 0.9 | | 1.0 | | 1.0 | | ns |
| t _{ODEH} | Output Data Enable Hold | 0.3 | | 0.4 | | 0.4 | | 0.5 | | 0.5 | | ns |
| f _{ODESU} | Output Data Enable Setup | 1.3 | | 1.5 | | 1.7 | | 2.0 | | 2.0 | | ns |

Notes:

1. The -2 and -3 speed grades have been discontinued. Refer to PDN 0104, PDN 0203, PDN 0604, and PDN 1004 at http://www.microsemi.com/soc/support/notifications/default.aspx#pdn.

 Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual worst-case performance. Post-route timing is based on actual routing delay measurements performed on the device prior to shipment.



A1440A, A14V40A Timing Characteristics (continued)

Table 2-28 • A1440A, A14V40A Worst-Case Commercial Conditions, VCC = 4.75 V, T_J = 70°C

| I/O Moo | dule – TTL Output Timing ¹ | -3 Sp | beed ² | -2 Sp | beed ² | –1 S | peed | Std. | Speed | 3.3 V | Speed ¹ | Units |
|--------------------|--|-------|-------------------|-------|-------------------|------|------|------|-------|-------|--------------------|-------|
| Parame | eter/Description | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | |
| t _{DHS} | Data to Pad, High Slew | | 5.0 | | 5.6 | | 6.4 | | 7.5 | | 9.8 | ns |
| t _{DLS} | Data to Pad, Low Slew | | 8.0 | | 9.0 | | 10.2 | | 12.0 | | 15.6 | ns |
| t _{ENZHS} | Enable to Pad, Z to H/L, High Slew | | 4.0 | | 4.5 | | 5.1 | | 6.0 | | 7.8 | ns |
| t _{ENZLS} | Enable to Pad, Z to H/L, Low Slew | | 7.4 | | 8.3 | | 9.4 | | 11.0 | | 14.3 | ns |
| t _{ENHSZ} | Enable to Pad, H/L to Z, High Slew | | 7.4 | | 8.3 | | 9.4 | | 11.0 | | 14.3 | ns |
| t _{ENLSZ} | Enable to Pad, H/L to Z, Low Slew | | 7.4 | | 8.3 | | 9.4 | | 11.0 | | 14.3 | ns |
| t _{CKHS} | IOCLK Pad to Pad H/L, High Slew | | 8.5 | | 8.5 | | 9.5 | | 11.0 | | 14.3 | ns |
| t _{CKLS} | IOCLK Pad to Pad H/L, Low Slew | | 11.3 | | 11.3 | | 13.5 | | 15.0 | | 19.5 | ns |
| d _{TLHHS} | Delta Low to High, High Slew | | 0.02 | | 0.02 | | 0.03 | | 0.03 | | 0.04 | ns/pF |
| d _{TLHLS} | Delta Low to High, Low Slew | | 0.05 | | 0.05 | | 0.06 | | 0.07 | | 0.09 | ns/pF |
| d _{THLHS} | Delta High to Low, High Slew | | 0.04 | | 0.04 | | 0.04 | | 0.05 | | 0.07 | ns/pF |
| d _{THLLS} | Delta High to Low, Low Slew | | 0.05 | | 0.05 | | 0.06 | | 0.07 | | 0.09 | ns/pF |
| I/O Moo | dule – CMOS Output Timing ¹ | • | | | • | | | | | | | |
| t _{DHS} | Data to Pad, High Slew | | 6.2 | | 7.0 | | 7.9 | | 9.3 | | 12.1 | ns |
| t _{DLS} | Data to Pad, Low Slew | | 11.7 | | 13.1 | | 14.9 | | 17.5 | | 22.8 | ns |
| t _{ENZHS} | Enable to Pad, Z to H/L, High Slew | | 5.2 | | 5.9 | | 6.6 | | 7.8 | | 10.1 | ns |
| t _{ENZLS} | Enable to Pad, Z to H/L, Low Slew | | 8.9 | | 10.0 | | 11.3 | | 13.3 | | 17.3 | ns |
| t _{ENHSZ} | Enable to Pad, H/L to Z, High Slew | | 7.4 | | 8.3 | | 9.4 | | 11.0 | | 14.3 | ns |
| t _{ENLSZ} | Enable to Pad, H/L to Z, Low Slew | | 7.4 | | 8.3 | | 9.4 | | 11.0 | | 14.3 | ns |
| t _{CKHS} | IOCLK Pad to Pad H/L, High Slew | | 9.0 | | 9.0 | | 10.1 | | 11.8 | | 14.3 | ns |
| t _{CKLS} | IOCLK Pad to Pad H/L, Low Slew | | 13.0 | | 13.0 | | 15.6 | | 17.3 | | 22.5 | ns |
| d _{TLHHS} | Delta Low to High, High Slew | | 0.04 | | 0.04 | | 0.05 | | 0.06 | | 0.08 | ns/pF |
| d _{TLHLS} | Delta Low to High, Low Slew | | 0.07 | | 0.08 | | 0.09 | | 0.11 | | 0.14 | ns/pF |
| d _{THLHS} | Delta High to Low, High Slew | | 0.03 | | 0.03 | | 0.03 | | 0.04 | | 0.05 | ns/pF |
| d _{THLLS} | Delta High to Low, Low Slew | | 0.04 | | 0.04 | | 0.04 | | 0.05 | | 0.07 | ns/pF |

Notes:

1. Delays based on 35 pF loading.

2. The –2 and –3 speed grades have been discontinued. Refer to PDN 0104, PDN 0203, PDN 0604, and PDN 1004 at http://www.microsemi.com/soc/support/notifications/default.aspx#pdn.

A1440A, A14V40A Timing Characteristics (continued)

Table 2-29 • A1440A, A14V40A Worst-Case Commercial Conditions, VCC = 4.75 V, T_J = 70°C

| Dedicate | d (hardwired) I/O Clock Network | -3 Sp | beed ¹ | -2 Sp | beed ¹ | –1 S | peed | Std. | Speed | 3.3 V | Speed ¹ | Units |
|----------------------|---|------------|-------------------|------------|-------------------|------------|------------|------------|------------|------------|--------------------|-------|
| Paramete | er/Description | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | |
| t _{IOCKH} | Input Low to High (pad to I/O module input) | | 2.0 | | 2.3 | | 2.6 | | 3.0 | | 3.5 | ns |
| t _{IOPWH} | Minimum Pulse Width High | 1.9 | | 2.4 | | 3.3 | | 3.8 | | 4.8 | | ns |
| t _{IPOWL} | Minimum Pulse Width Low | 1.9 | | 2.4 | | 3.3 | | 3.8 | | 4.8 | | ns |
| t _{IOSAPW} | Minimum Asynchronous Pulse Width | 1.9 | | 2.4 | | 3.3 | | 3.8 | | 4.8 | | ns |
| t _{IOCKSW} | Maximum Skew | | 0.4 | | 0.4 | | 0.4 | | 0.4 | | 0.4 | ns |
| t _{IOP} | Minimum Period | 4.0 | | 5.0 | | 6.8 | | 8.0 | | 10.0 | | ns |
| f _{IOMAX} | Maximum Frequency | | 250 | | 200 | | 150 | | 125 | | 100 | MHz |
| Dedicate | d (hardwired) Array Clock | | | | | | | | | | | |
| ^t нскн | Input Low to High (pad to S-module input) | | 3.0 | | 3.4 | | 3.9 | | 4.5 | | 5.5 | ns |
| ^t HCKL | Input High to Low (pad to S-module input) | | 3.0 | | 3.4 | | 3.9 | | 4.5 | | 5.5 | ns |
| t _{HPWH} | Minimum Pulse Width High | 1.9 | | 2.4 | | 3.3 | | 3.8 | | 4.8 | | ns |
| t _{HPWL} | Minimum Pulse Width Low | 1.9 | | 2.4 | | 3.3 | | 3.8 | | 4.8 | | ns |
| t _{HCKSW} | Delta High to Low, Low Slew | | 0.3 | | 0.3 | | 0.3 | | 0.3 | | 0.3 | ns |
| t _{HP} | Minimum Period | 4.0 | | 5.0 | | 6.8 | | 8.0 | | 10.0 | | ns |
| f _{HMAX} | Maximum Frequency | | 250 | | 200 | | 150 | | 125 | | 100 | MHz |
| Routed A | hrray Clock Networks | • | | | | | | • | - | | | |
| t _{RCKH} | Input Low to High (FO = 64) | | 3.7 | | 4.1 | | 4.7 | | 5.5 | | 9.0 | ns |
| t _{RCKL} | Input High to Low (FO = 64) | | 4.0 | | 4.5 | | 5.1 | | 6.0 | | 9.0 | ns |
| t _{RPWH} | Min. Pulse Width High (FO = 64) | 3.3 | | 3.8 | | 4.2 | | 4.9 | | 6.5 | | ns |
| t _{RPWL} | Min. Pulse Width Low (FO = 64) | 3.3 | | 3.8 | | 4.2 | | 4.9 | | 6.5 | | ns |
| t _{RCKSW} | Maximum Skew (FO = 128) | | 0.7 | | 0.8 | | 0.9 | | 1.0 | | 1.0 | ns |
| t _{RP} | Minimum Period (FO = 64) | 6.8 | | 8.0 | | 8.7 | | 10.0 | | 13.4 | | ns |
| f _{RMAX} | Maximum Frequency (FO = 64) | | 150 | | 125 | | 115 | | 100 | | 75 | MHz |
| Clock-to- | Clock Skews | | | | | - | | | | | | |
| t _{IOHCKSW} | I/O Clock to H-Clock Skew | 0.0 | 1.7 | 0.0 | 1.8 | 0.0 | 2.0 | 0.0 | 2.2 | 0.0 | 3.0 | ns |
| t _{IORCKSW} | I/O Clock to R-Clock Skew (FO = 64) (FO = 144) | 0.0 0.0 | 1.0 3.0 | 0.0 0.0 | 1.0 3.0 | 0.0 0.0 | 1.0 3.0 | 0.0 0.0 | 1.0 3.0 | 0.0 0.0 | 3.0 3.0 | ns |
| t _{HRCKSW} | H-Clock to R-Clock Skew (FO = 64) (FO = 144) | 0.0 0.0 | 1.0 3.0 | 0.0 0.0 | 1.0 3.0 | 0.0 0.0 | 1.0 3.0 | 0.0 0.0 | 1.0 3.0 | 0.0 0.0 | 1.0 3.0 | ns |

Notes:

1. The -2 and -3 speed grades have been discontinued. Refer to PDN 0104, PDN 0203, PDN 0604, and PDN 1004 at http://www.microsemi.com/soc/support/notifications/default.aspx#pdn.

2. Delays based on 35 pF loading.



A1460A, A14V60A Timing Characteristics

| Table 2-30 • A1460A | , A14V60A Worst-Case Commercial | Conditions | $VCC = 4.75 V_{1} T_{1} = 70^{\circ}C^{1}$ |
|---------------------|---------------------------------|------------|--|
| | | oonantiono | |

| Logic N | Iodule Propagation Delays ² | -3 S | peed ³ | –2 Sp | beed ³ | –1 S | peed | Std. Speed | | 3.3 V Speed ¹ | | Units |
|--------------------|--|------|-------------------|-------|-------------------|------|------|------------|------|--------------------------|------|-------|
| Parame | eter/Description | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | |
| t _{PD} | Internal Array Module | | 2.0 | | 2.3 | | 2.6 | | 3.0 | | 3.9 | ns |
| t _{CO} | Sequential Clock to Q | | 2.0 | | 2.3 | | 2.6 | | 3.0 | | 3.9 | ns |
| t _{CLR} | Asynchronous Clear to Q | | 2.0 | | 2.3 | | 2.6 | | 3.0 | | 3.9 | ns |
| Predict | ed Routing Delays ⁴ | | | | | | | | | | | |
| t _{RD1} | FO = 1 Routing Delay | | 0.9 | | 1.0 | | 1.1 | | 1.3 | | 1.7 | ns |
| t _{RD2} | FO = 2 Routing Delay | | 1.2 | | 1.4 | | 1.6 | | 1.8 | | 2.4 | ns |
| t _{RD3} | FO = 3 Routing Delay | | 1.4 | | 1.6 | | 1.8 | | 2.1 | | 2.8 | ns |
| t _{RD4} | FO = 4 Routing Delay | | 1.7 | | 1.9 | | 2.2 | | 2.5 | | 3.3 | ns |
| t _{RD8} | FO = 8 Routing Delay | | 2.8 | | 3.2 | | 3.6 | | 4.2 | | 5.5 | ns |
| Logic N | Nodule Sequential Timing | | | | | | | | | | | |
| t _{SUD} | Flip-Flop Data Input Setup | 0.5 | | 0.6 | | 0.7 | | 0.8 | | 0.8 | | ns |
| t _{HD} | Flip-Flop Data Input Hold | 0.0 | | 0.0 | | 0.0 | | 0.0 | | 0.0 | | ns |
| t _{SUD} | Latch Data Input Setup | 0.5 | | 0.6 | | 0.7 | | 0.8 | | 0.8 | | ns |
| t _{HD} | Latch Data Input Hold | 0.0 | | 0.0 | | 0.0 | | 0.0 | | 0.0 | | ns |
| t _{WASYN} | Asynchronous Pulse Width | 2.4 | | 3.2 | | 3.8 | | 4.8 | | 6.5 | | ns |
| t _{WCLKA} | Flip-Flop Clock Pulse Width | 2.4 | | 3.2 | | 3.8 | | 4.8 | | 6.5 | | ns |
| t _A | Flip-Flop Clock Input Period | 5.0 | | 6.8 | | 8.0 | | 10.0 | | 13.4 | | ns |
| f _{MAX} | Flip-Flop Clock Frequency | | 200 | | 150 | | 125 | | 100 | | 75 | MHz |

Notes:

1. VCC = 3.0 V for 3.3 V specifications.

2. For dual-module macros, use $t_{PD} + t_{RD1} + t_{PDn} + t_{CO} + t_{RD1} + t_{PDn}$ or $t_{PD1} + t_{RD1} + t_{SUD}$, whichever is appropriate.

3. The –2 and –3 speed grades have been discontinued. Refer to PDN 0104, PDN 0203, PDN 0604, and PDN 1004 at http://www.microsemi.com/soc/support/notifications/default.aspx#pdn.

4. Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual worst-case performance. Post-route timing is based on actual routing delay measurements performed on the device prior to shipment.

A1460A, A14V60A Timing Characteristics (continued)

| Table 2-31 • A1460A | A14V60A Worst-Case | Commercial Conditions | , VCC = 4.75 V, T _J = 70°C |
|-----------------------|---------------------|-----------------------|---------------------------------------|
| Table 2-31 • A 1400A, | A 14VOUA WUISI-Case | Commercial Conditions | , VCC = 4.75 V, Ij = 70 C |

| I/O Moc | dule Input Propagation Delays | -3 Sp | beed ¹ | -2 Sp | beed ¹ | –1 S | -1 Speed Std. | | | . Speed 3.3 V Spe | | Units |
|--------------------|--------------------------------------|-------|-------------------|-------|-------------------|------|---------------|------|------|-------------------|------|-------|
| Parame | eter/Description | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | |
| t _{INY} | Input Data Pad to Y | | 2.8 | | 3.2 | | 3.6 | | 4.2 | | 5.5 | ns |
| t _{ICKY} | Input Reg IOCLK Pad to Y | | 4.7 | | 5.3 | | 6.0 | | 7.0 | | 9.2 | ns |
| t _{OCKY} | Output Reg IOCLK Pad to Y | | 4.7 | | 5.3 | | 6.0 | | 7.0 | | 9.2 | ns |
| t _{ICLRY} | Input Asynchronous Clear to Y | | 4.7 | | 5.3 | | 6.0 | | 7.0 | | 9.2 | ns |
| t _{OCLRY} | Output Asynchronous Clear to Y | | 4.7 | | 5.3 | | 6.0 | | 7.0 | | 9.2 | ns |
| Predict | ed Input Routing Delays ² | | | | • | | • | | | | | |
| t _{RD1} | FO = 1 Routing Delay | | 0.9 | | 1.0 | | 1.1 | | 1.3 | | 1.7 | ns |
| t _{RD2} | FO = 2 Routing Delay | | 1.2 | | 1.4 | | 1.6 | | 1.8 | | 2.4 | ns |
| t _{RD3} | FO = 3 Routing Delay | | 1.4 | | 1.6 | | 1.8 | | 2.1 | | 2.8 | ns |
| t _{RD4} | FO = 4 Routing Delay | | 1.7 | | 1.9 | | 2.2 | | 2.5 | | 3.3 | ns |
| t _{RD8} | FO = 8 Routing Delay | | 2.8 | | 3.2 | | 3.6 | | 4.2 | | 5.5 | ns |
| I/O Moc | dule Sequential Timing (wrt IOCLK | pad) | | | • | | • | | | | | |
| t _{INH} | Input F-F Data Hold | 0.0 | | 0.0 | | 0.0 | | 0.0 | | 0.0 | | ns |
| t _{INSU} | Input F-F Data Setup | 1.3 | | 1.5 | | 1.8 | | 2.0 | | 2.0 | | ns |
| t _{IDEH} | Input Data Enable Hold | 0.0 | | 0.0 | | 0.0 | | 0.0 | | 0.0 | | ns |
| t _{IDESU} | Input Data Enable Setup | 5.8 | | 6.5 | | 7.5 | | 8.6 | | 8.6 | | ns |
| t _{OUTH} | Output F-F Data hold | 0.7 | | 0.8 | | 0.9 | | 1.0 | | 1.0 | | ns |
| t _{OUTSU} | Output F-F Data Setup | 0.7 | | 0.8 | | 0.9 | | 1.0 | | 1.0 | | ns |
| t _{ODEH} | Output Data Enable Hold | 0.3 | | 0.4 | | 0.4 | | 0.5 | | 0.5 | | ns |
| f _{ODESU} | Output Data Enable Setup | 1.3 | | 1.5 | | 1.7 | | 2.0 | | 2.0 | | ns |

Notes:

5. The –2 and –3 speed grades have been discontinued. Refer to PDN 0104, PDN 0203, PDN 0604, and PDN 1004 at http://www.microsemi.com/soc/support/notifications/default.aspx#pdn.

6. Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual worst-case performance. Post-route timing is based on actual routing delay measurements performed on the device prior to shipment.



A1460A, A14V60A Timing Characteristics (continued)

Table 2-32 • A1460A, A14V60A Worst-Case Commercial Conditions, VCC = 4.75 V, T_J = 70°C

| I/O Moo | dule – TTL Output Timing ¹ | –3 Sj | beed ² | -2 Sp | beed ² | –1 S | peed | Std. | Speed | I 3.3 V Speed ¹ | | Units |
|--------------------|--|-------|-------------------|-------|-------------------|------|------|------|-------|----------------------------|------|-------|
| Parame | eter/Description | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | |
| t _{DHS} | Data to Pad, High Slew | | 5.0 | | 5.6 | | 6.4 | | 7.5 | | 9.8 | ns |
| t _{DLS} | Data to Pad, Low Slew | | 8.0 | | 9.0 | | 10.2 | | 12.0 | | 15.6 | ns |
| t _{ENZHS} | Enable to Pad, Z to H/L, High Slew | | 4.0 | | 4.5 | | 5.1 | | 6.0 | | 7.8 | ns |
| t _{ENZLS} | Enable to Pad, Z to H/L, Low Slew | | 7.4 | | 8.3 | | 9.4 | | 11.0 | | 14.3 | ns |
| t _{ENHSZ} | Enable to Pad, H/L to Z, High Slew | | 7.8 | | 8.7 | | 9.9 | | 11.6 | | 15.1 | ns |
| t _{ENLSZ} | Enable to Pad, H/L to Z, Low Slew | | 7.4 | | 8.3 | | 9.4 | | 11.0 | | 14.3 | ns |
| t _{CKHS} | IOCLK Pad to Pad H/L, High Slew | | 9.0 | | 9.0 | | 10.0 | | 11.5 | | 15.0 | ns |
| t _{CKLS} | IOCLK Pad to Pad H/L, Low Slew | | 12.8 | | 12.8 | | 15.3 | | 17.0 | | 22.1 | ns |
| d _{TLHHS} | Delta Low to High, High Slew | | 0.02 | | 0.02 | | 0.03 | | 0.03 | | 0.04 | ns/pF |
| d _{TLHLS} | Delta Low to High, Low Slew | | 0.05 | | 0.05 | | 0.06 | | 0.07 | | 0.09 | ns/pF |
| d _{THLHS} | Delta High to Low, High Slew | | 0.04 | | 0.04 | | 0.04 | | 0.05 | | 0.07 | ns/pF |
| d _{THLLS} | Delta High to Low, Low Slew | | 0.05 | | 0.05 | | 0.06 | | 0.07 | | 0.09 | ns/pF |
| I/O Moo | dule – CMOS Output Timing ¹ | • | | | • | | • | | | | | |
| t _{DHS} | Data to Pad, High Slew | | 6.2 | | 7.0 | | 7.9 | | 9.3 | | 12.1 | ns |
| t _{DLS} | Data to Pad, Low Slew | | 11.7 | | 13.1 | | 14.9 | | 17.5 | | 22.8 | ns |
| t _{ENZHS} | Enable to Pad, Z to H/L, High Slew | | 5.2 | | 5.9 | | 6.6 | | 7.8 | | 10.1 | ns |
| t _{ENZLS} | Enable to Pad, Z to H/L, Low Slew | | 8.9 | | 10.0 | | 11.3 | | 13.3 | | 17.3 | ns |
| t _{ENHSZ} | Enable to Pad, H/L to Z, High Slew | | 7.4 | | 8.3 | | 9.4 | | 11.0 | | 14.3 | ns |
| t _{ENLSZ} | Enable to Pad, H/L to Z, Low Slew | | 7.4 | | 8.3 | | 9.4 | | 11.0 | | 14.3 | ns |
| t _{CKHS} | IOCLK Pad to Pad H/L, High Slew | | 10.4 | | 10.4 | | 12.1 | | 13.8 | | 17.9 | ns |
| t _{CKLS} | IOCLK Pad to Pad H/L, Low Slew | | 14.5 | | 14.5 | | 17.4 | | 19.3 | | 25.1 | ns |
| d _{TLHHS} | Delta Low to High, High Slew | | 0.04 | | 0.04 | | 0.05 | | 0.06 | | 0.08 | ns/pF |
| d _{TLHLS} | Delta Low to High, Low Slew | | 0.07 | | 0.08 | | 0.09 | | 0.11 | | 0.14 | ns/pF |
| d _{THLHS} | Delta High to Low, High Slew | | 0.03 | | 0.03 | | 0.03 | | 0.04 | | 0.05 | ns/pF |
| d _{THLLS} | Delta High to Low, Low Slew | | 0.04 | | 0.04 | | 0.04 | | 0.05 | | 0.07 | ns/pF |

Notes:

1. Delays based on 35 pF loading.

2. The –2 and –3 speed grades have been discontinued. Refer to PDN 0104, PDN 0203, PDN 0604, and PDN 1004 at http://www.microsemi.com/soc/support/notifications/default.aspx#pdn.

A1460A, A14V60A Timing Characteristics (continued)

| Table 2 22 . A1460A | A14V60A Warst Casa | Commercial Conditions | |
|------------------------|----------------------|-----------------------|---------------------------------------|
| 1 able 2-33 • A 1400A, | A 14 VOUA WUISI-Case | Commercial Conditions | , VCC = 4.75 V, T _J = 70°C |

| Dedicate | d (hardwired) I/O Clock Network | -3 Sp | beed ¹ | –2 Speed ¹ | | -1 Speed | | Std. Speed | | I 3.3 V Speed ¹ | | Units |
|----------------------|---|------------|-------------------|-----------------------|------------|------------|------------|------------|------------|----------------------------|------------|-------|
| Paramete | er/Description | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | |
| t _{IOCKH} | Input Low to High (pad to I/O module input) | | 2.3 | | 2.6 | | 3.0 | | 3.5 | | 4.5 | ns |
| t _{IOPWH} | Minimum Pulse Width High | 2.4 | | 3.2 | | 3.8 | | 4.8 | | 6.5 | | ns |
| t _{IPOWL} | Minimum Pulse Width Low | 2.4 | | 3.2 | | 3.8 | | 4.8 | | 6.5 | | ns |
| t _{IOSAPW} | Minimum Asynchronous Pulse Width | 2.4 | | 3.2 | | 3.8 | | 4.8 | | 6.5 | | ns |
| t _{IOCKSW} | Maximum Skew | | 0.6 | | 0.6 | | 0.6 | | 0.6 | | 0.6 | ns |
| t _{IOP} | Minimum Period | 5.0 | | 6.8 | | 8.0 | | 10.0 | | 13.4 | | ns |
| f _{IOMAX} | Maximum Frequency | | 200 | | 150 | | 125 | | 100 | | 75 | MHz |
| Dedicate | d (hardwired) Array Clock | | | | | | | | | | | |
| ^t нскн | Input Low to High (pad to S-module input) | | 3.7 | | 4.1 | | 4.7 | | 5.5 | | 7.0 | ns |
| t _{HCKL} | Input High to Low (pad to S-module input) | | 3.7 | | 4.1 | | 4.7 | | 5.5 | | 7.0 | ns |
| t _{HPWH} | Minimum Pulse Width High | 2.4 | | 3.2 | | 3.8 | | 4.8 | | 6.5 | | ns |
| t _{HPWL} | Minimum Pulse Width Low | 2.4 | | 3.2 | | 3.8 | | 4.8 | | 6.5 | | ns |
| t _{HCKSW} | Delta High to Low, Low Slew | | 0.6 | | 0.6 | | 0.6 | | 0.6 | | 0.6 | ns |
| t _{HP} | Minimum Period | 5.0 | | 6.8 | | 8.0 | | 10.0 | | 13.4 | | ns |
| f _{HMAX} | Maximum Frequency | | 200 | | 150 | | 125 | | 100 | | 75 | MHz |
| Routed A | rray Clock Networks | • | | • | | | | | - | | | |
| t _{RCKH} | Input Low to High (FO = 64) | | 6.0 | | 6.8 | | 7.7 | | 9.0 | | 11.8 | ns |
| t _{RCKL} | Input High to Low (FO = 64) | | 6.0 | | 6.8 | | 7.7 | | 9.0 | | 11.8 | ns |
| t _{RPWH} | Min. Pulse Width High (FO = 64) | 4.1 | | 4.5 | | 5.4 | | 6.1 | | 8.2 | | ns |
| t _{RPWL} | Min. Pulse Width Low (FO = 64) | 4.1 | | 4.5 | | 5.4 | | 6.1 | | 8.2 | | ns |
| t _{RCKSW} | Maximum Skew (FO = 128) | | 1.2 | | 1.4 | | 1.6 | | 1.8 | | 1.8 | ns |
| t _{RP} | Minimum Period (FO = 64) | 8.3 | | 9.3 | | 11.1 | | 12.5 | | 16.7 | | ns |
| f _{RMAX} | Maximum Frequency (FO = 64) | | 120 | | 105 | | 90 | | 80 | | 60 | MHz |
| Clock-to- | Clock Skews | • | | • | | | | | - | | | |
| t _{IOHCKSW} | I/O Clock to H-Clock Skew | 0.0 | 2.6 | 0.0 | 2.7 | 0.0 | 2.9 | 0.0 | 3.0 | 0.0 | 3.0 | ns |
| t _{IORCKSW} | I/O Clock to R-Clock Skew (FO = 64) (FO = 216) | 0.0 0.0 | 1.7 5.0 | 0.0 0.0 | 1.7 5.0 | 0.0 0.0 | 1.7 5.0 | 0.0 0.0 | 1.7 5.0 | 0.0 0.0 | 5.0 5.0 | ns |
| t _{HRCKSW} | H-Clock to R-Clock Skew (FO = 64) (FO = 216) | 0.0 0.0 | 1.3 3.0 | 0.0 0.0 | 1.0 3.0 | 0.0 0.0 | 1.0 3.0 | 0.0 0.0 | 1.0 3.0 | 0.0 0.0 | 1.0 3.0 | ns |

Notes:

1. The -2 and -3 speed grades have been discontinued. Refer to PDN 0104, PDN 0203, PDN 0604, and PDN 1004 at http://www.microsemi.com/soc/support/notifications/default.aspx#pdn.

2. Delays based on 35 pF loading.



A14100A, A14V100A Timing Characteristics

| Logic N | Iodule Propagation Delays ² | -3 S | peed ³ | -2 Sp | beed ³ | –1 S | peed | Std. S | speed | 3.3 V | 3.3 V Speed ¹ | |
|--------------------|--|------|-------------------|-------|-------------------|------|------|--------|-------|-------|--------------------------|-----|
| Parame | eter/Description | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | 1 |
| t _{PD} | Internal Array Module | | 2.0 | | 2.3 | | 2.6 | | 3.0 | | 3.9 | ns |
| t _{CO} | Sequential Clock to Q | | 2.0 | | 2.3 | | 2.6 | | 3.0 | | 3.9 | ns |
| t _{CLR} | Asynchronous Clear to Q | | 2.0 | | 2.3 | | 2.6 | | 3.0 | | 3.9 | ns |
| Predict | ed Routing Delays ⁴ | | | | | | | | | | | |
| t _{RD1} | FO = 1 Routing Delay | | 0.9 | | 1.0 | | 1.1 | | 1.3 | | 1.7 | ns |
| t _{RD2} | FO = 2 Routing Delay | | 1.2 | | 1.4 | | 1.6 | | 1.8 | | 2.4 | ns |
| t _{RD3} | FO = 3 Routing Delay | | 1.4 | | 1.6 | | 1.8 | | 2.1 | | 2.8 | ns |
| t _{RD4} | FO = 4 Routing Delay | | 1.7 | | 1.9 | | 2.2 | | 2.5 | | 3.3 | ns |
| t _{RD8} | FO = 8 Routing Delay | | 2.8 | | 3.2 | | 3.6 | | 4.2 | | 5.5 | ns |
| Logic N | Nodule Sequential Timing | | | | | | | | | | | |
| t _{SUD} | Flip-Flop Data Input Setup | 0.5 | | 0.6 | | 0.8 | | 0.8 | | 0.8 | | ns |
| t _{HD} | Flip-Flop Data Input Hold | 0.0 | | 0.0 | | 0.5 | | 0.5 | | 0.5 | | ns |
| t _{SUD} | Latch Data Input Setup | 0.5 | | 0.6 | | 0.8 | | 0.8 | | 0.8 | | ns |
| t _{HD} | Latch Data Input Hold | 0.0 | | 0.0 | | 0.5 | | 0.5 | | 0.5 | | ns |
| t _{WASYN} | Asynchronous Pulse Width | 2.4 | | 3.2 | | 3.8 | | 4.8 | | 6.5 | | ns |
| t _{WCLKA} | Flip-Flop Clock Pulse Width | 2.4 | | 3.2 | | 3.8 | | 4.8 | | 6.5 | | ns |
| t _A | Flip-Flop Clock Input Period | 5.0 | | 6.8 | | 8.0 | | 10.0 | | 13.4 | | ns |
| f _{MAX} | Flip-Flop Clock Frequency | | 200 | | 150 | | 125 | | 100 | | 75 | MHz |

Notes:

1. VCC = 3.0 V for 3.3 V specifications.

2. For dual-module macros, use $t_{PD} + t_{RD1} + t_{PDn} + t_{CO} + t_{RD1} + t_{PDn}$ or $t_{PD1} + t_{RD1} + t_{SUD}$, whichever is appropriate.

3. The –2 and –3 speed grades have been discontinued. Refer to PDN 0104, PDN 0203, PDN 0604, and PDN 1004 at http://www.microsemi.com/soc/support/notifications/default.aspx#pdn.

4. Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual worst-case performance. Post-route timing is based on actual routing delay measurements performed on the device prior to shipment.

A14100A, A14V100A Timing Characteristics (continued)

Table 2-35 • A14100A, A14V100A Worst-Case Commercial Conditions, VCC = 4.75 V, T_J = 70°C

| I/O Moc | ule Input Propagation Delays | -3 Sp | beed ¹ | -2 Sp | beed ¹ | –1 S | peed | Std. | Speed | 3.3 V Speed ¹ | | Units |
|-----------------------|--------------------------------------|-------|-------------------|-------|-------------------|------|------|------|-------|--------------------------|------|-------|
| Parameter/Description | | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | |
| t _{INY} | Input Data Pad to Y | | 2.8 | | 3.2 | | 3.6 | | 4.2 | | 5.5 | ns |
| t _{ICKY} | Input Reg IOCLK Pad to Y | | 4.7 | | 5.3 | | 6.0 | | 7.0 | | 9.2 | ns |
| t _{OCKY} | Output Reg IOCLK Pad to Y | | 4.7 | | 5.3 | | 6.0 | | 7.0 | | 9.2 | ns |
| t _{ICLRY} | Input Asynchronous Clear to Y | | 4.7 | | 5.3 | | 6.0 | | 7.0 | | 9.2 | ns |
| t _{OCLRY} | Output Asynchronous Clear to Y | | 4.7 | | 5.3 | | 6.0 | | 7.0 | | 9.2 | ns |
| Predict | ed Input Routing Delays ² | | | | | | | | | | | |
| t _{RD1} | FO = 1 Routing Delay | | 0.9 | | 1.0 | | 1.1 | | 1.3 | | 1.7 | ns |
| t _{RD2} | FO = 2 Routing Delay | | 1.2 | | 1.4 | | 1.6 | | 1.8 | | 2.4 | ns |
| t _{RD3} | FO = 3 Routing Delay | | 1.4 | | 1.6 | | 1.8 | | 2.1 | | 2.8 | ns |
| t _{RD4} | FO = 4 Routing Delay | | 1.7 | | 1.9 | | 2.2 | | 2.5 | | 3.3 | ns |
| t _{RD8} | FO = 8 Routing Delay | | 2.8 | | 3.2 | | 3.6 | | 4.2 | | 5.5 | ns |
| I/O Moc | ule Sequential Timing (wrt IOCLK | pad) | | | | | | | | | | |
| t _{INH} | Input F-F Data Hold | 0.0 | | 0.0 | | 0.0 | | 0.0 | | 0.0 | | ns |
| t _{INSU} | Input F-F Data Setup | 1.2 | | 1.4 | | 1.5 | | 1.8 | | 1.8 | | ns |
| t _{IDEH} | Input Data Enable Hold | 0.0 | | 0.0 | | 0.0 | | 0.0 | | 0.0 | | ns |
| t _{IDESU} | Input Data Enable Setup | 5.8 | | 6.5 | | 7.5 | | 8.6 | | 8.6 | | ns |
| t _{OUTH} | Output F-F Data hold | 0.7 | | 0.8 | | 1.0 | | 1.0 | | 1.0 | | ns |
| t _{OUTSU} | Output F-F Data Setup | 0.7 | | 0.8 | | 1.0 | | 1.0 | | 1.0 | | ns |
| t _{ODEH} | Output Data Enable Hold | 0.3 | | 0.4 | | 0.5 | | 0.5 | | 0.5 | | ns |
| f _{ODESU} | Output Data Enable Setup | 1.3 | | 1.5 | | 2.0 | | 2.0 | | 2.0 | | ns |

Notes: *

1. The –2 and –3 speed grades have been discontinued. Refer to PDN 0104, PDN 0203, PDN 0604, and PDN 1004 at http://www.microsemi.com/soc/support/notifications/default.aspx#pdn.

 Routing delays are for typical designs across worst-case operating conditions. These parameters should be used for estimating device performance. Post-route timing analysis or simulation is required to determine actual worst-case performance. Post-route timing is based on actual routing delay measurements performed on the device prior to shipment.



A14100A, A14V100A Timing Characteristics (continued)

Table 2-36 • A14100A, A14V100A Worst-Case Commercial Conditions, VCC = 4.75 V, T_J = 70°C

| I/O Moc | dule – TTL Output Timing ¹ | –3 SI | beed ² | -2 Sp | beed ² | –1 S | peed | Std. | Speed | 3.3 V | Speed ¹ | Units |
|--------------------|--|-------|-------------------|-------|-------------------|------|------|------|-------|-------|--------------------|-------|
| Parame | eter/Description | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | |
| t _{DHS} | Data to Pad, High Slew | | 5.0 | | 5.6 | | 6.4 | | 7.5 | | 9.8 | ns |
| t _{DLS} | Data to Pad, Low Slew | | 8.0 | | 9.0 | | 10.2 | | 12.0 | | 15.6 | ns |
| t _{ENZHS} | Enable to Pad, Z to H/L, High Slew | | 4.0 | | 4.5 | | 5.1 | | 6.0 | | 7.8 | ns |
| t _{ENZLS} | Enable to Pad, Z to H/L, Low Slew | | 7.4 | | 8.3 | | 9.4 | | 11.0 | | 14.3 | ns |
| t _{ENHSZ} | Enable to Pad, H/L to Z, High Slew | | 8.0 | | 9.0 | | 10.2 | | 12.0 | | 15.6 | ns |
| t _{ENLSZ} | Enable to Pad, H/L to Z, Low Slew | | 7.4 | | 8.3 | | 9.4 | | 11.0 | | 14.3 | ns |
| t _{CKHS} | IOCLK Pad to Pad H/L, High Slew | | 9.5 | | 9.5 | | 10.5 | | 12.0 | | 15.6 | ns |
| t _{CKLS} | IOCLK Pad to Pad H/L, Low Slew | | 12.8 | | 12.8 | | 15.3 | | 17.0 | | 22.1 | ns |
| d _{TLHHS} | Delta Low to High, High Slew | | 0.02 | | 0.02 | | 0.03 | | 0.03 | | 0.04 | ns/pF |
| d _{TLHLS} | Delta Low to High, Low Slew | | 0.05 | | 0.05 | | 0.06 | | 0.07 | | 0.09 | ns/pF |
| d _{THLHS} | Delta High to Low, High Slew | | 0.04 | | 0.04 | | 0.04 | | 0.05 | | 0.07 | ns/pF |
| d _{THLLS} | Delta High to Low, Low Slew | | 0.05 | | 0.05 | | 0.06 | | 0.07 | | 0.09 | ns/pF |
| I/O Moc | dule – CMOS Output Timing ¹ | | | | | | | | | | | |
| t _{DHS} | Data to Pad, High Slew | | 6.2 | | 7.0 | | 7.9 | | 9.3 | | 12.1 | ns |
| t _{DLS} | Data to Pad, Low Slew | | 11.7 | | 13.1 | | 14.9 | | 17.5 | | 22.8 | ns |
| t _{ENZHS} | Enable to Pad, Z to H/L, High Slew | | 5.2 | | 5.9 | | 6.6 | | 7.8 | | 10.1 | ns |
| t _{ENZLS} | Enable to Pad, Z to H/L, Low Slew | | 8.9 | | 10.0 | | 11.3 | | 13.3 | | 17.3 | ns |
| t _{ENHSZ} | Enable to Pad, H/L to Z, High Slew | | 8.0 | | 9.0 | | 10.0 | | 12.0 | | 15.6 | ns |
| t _{ENLSZ} | Enable to Pad, H/L to Z, Low Slew | | 7.4 | | 8.3 | | 9.4 | | 11.0 | | 14.3 | ns |
| t _{CKHS} | IOCLK Pad to Pad H/L, High Slew | | 10.4 | | 10.4 | | 12.4 | | 13.8 | | 17.9 | ns |
| t _{CKLS} | IOCLK Pad to Pad H/L, Low Slew | | 14.5 | | 14.5 | | 17.4 | | 19.3 | | 25.1 | ns |
| d _{TLHHS} | Delta Low to High, High Slew | | 0.04 | | 0.04 | | 0.05 | | 0.06 | | 0.08 | ns/pF |
| d _{TLHLS} | Delta Low to High, Low Slew | | 0.07 | | 0.08 | | 0.09 | | 0.11 | | 0.14 | ns/pF |
| d _{THLHS} | Delta High to Low, High Slew | | 0.03 | | 0.03 | | 0.03 | | 0.04 | | 0.05 | ns/pF |
| d _{THLLS} | Delta High to Low, Low Slew | | 0.04 | | 0.04 | | 0.04 | | 0.05 | | 0.07 | ns/pF |

Notes: *

1. Delays based on 35 pF loading.

2. The –2 and –3 speed grades have been discontinued. Refer to PDN 0104, PDN 0203, PDN 0604, and PDN 1004 at http://www.microsemi.com/soc/support/notifications/default.aspx#pdn.

A14100A, A14V100A Timing Characteristics (continued)

Table 2-37 • A14100A, A14V100A Worst-Case Commercial Conditions, VCC = 4.75 V, T_J = 70°C

| Dedicate | d (hardwired) I/O Clock Network | -3 Sp | beed ¹ | -2 Sp | beed ¹ | –1 S | peed | Std. | Speed | 3.3 V | Speed ¹ | Units |
|----------------------|---|------------|-------------------|------------|-------------------|------------|------------|------------|------------|------------|--------------------|-------|
| Paramete | er/Description | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | |
| t _{IOCKH} | Input Low to High (pad to I/O module input) | | 2.3 | | 2.6 | | 3.0 | | 3.5 | | 4.5 | ns |
| t _{IOPWH} | Minimum Pulse Width High | 2.4 | | 3.3 | | 3.8 | | 4.8 | | 6.5 | | ns |
| t _{IPOWL} | Minimum Pulse Width Low | 2.4 | | 3.3 | | 3.8 | | 4.8 | | 6.5 | | ns |
| t _{IOSAPW} | Minimum Asynchronous Pulse Width | 2.4 | | 3.3 | | 3.8 | | 4.8 | | 6.5 | | ns |
| t _{IOCKSW} | Maximum Skew | | 0.6 | | 0.6 | | 0.7 | | 0.8 | | 0.6 | ns |
| t _{IOP} | Minimum Period | 5.0 | | 6.8 | | 8.0 | | 10.0 | | 13.4 | | ns |
| f _{IOMAX} | Maximum Frequency | | 200 | | 150 | | 125 | | 100 | | 75 | MHz |
| Dedicate | d (hardwired) Array Clock | | | | | | | | | | | |
| t _{HCKH} | Input Low to High (pad to S-module input) | | 3.7 | | 4.1 | | 4.7 | | 5.5 | | 7.0 | ns |
| t _{HCKL} | Input High to Low (pad to S-module input) | | 3.7 | | 4.1 | | 4.7 | | 5.5 | | 7.0 | ns |
| t _{HPWH} | Minimum Pulse Width High | 2.4 | | 3.3 | | 3.8 | | 4.8 | | 6.5 | | ns |
| t _{HPWL} | Minimum Pulse Width Low | 2.4 | | 3.3 | | 3.8 | | 4.8 | | 6.5 | | ns |
| t _{HCKSW} | Delta High to Low, Low Slew | | 0.6 | | 0.6 | | 0.7 | | 0.8 | | 0.6 | ns |
| t _{HP} | Minimum Period | 5.0 | | 6.8 | | 8.0 | | 10.0 | | 13.4 | | ns |
| f _{HMAX} | Maximum Frequency | | 200 | | 150 | | 125 | | 100 | | 75 | MHz |
| Routed A | rray Clock Networks | • | | | | | | • | | | | |
| t _{RCKH} | Input Low to High (FO = 64) | | 6.0 | | 6.8 | | 7.7 | | 9.0 | | 11.8 | ns |
| t _{RCKL} | Input High to Low (FO = 64) | | 6.0 | | 6.8 | | 7.7 | | 9.0 | | 11.8 | ns |
| t _{RPWH} | Min. Pulse Width High (FO = 64) | 4.1 | | 4.5 | | 5.4 | | 6.1 | | 8.2 | | ns |
| t _{RPWL} | Min. Pulse Width Low (FO = 64) | 4.1 | | 4.5 | | 5.4 | | 6.1 | | 8.2 | | ns |
| t _{RCKSW} | Maximum Skew (FO = 128) | | 1.2 | | 1.4 | | 1.6 | | 1.8 | | 1.8 | ns |
| t _{RP} | Minimum Period (FO = 64) | 8.3 | | 9.3 | | 11.1 | | 12.5 | | 16.7 | | ns |
| f _{RMAX} | Maximum Frequency (FO = 64) | | 120 | | 105 | | 90 | | 80 | | 60 | MHz |
| Clock-to- | Clock Skews | | | | | - | | | | | | |
| t _{IOHCKSW} | I/O Clock to H-Clock Skew | 0.0 | 2.6 | 0.0 | 2.7 | 0.0 | 2.9 | 0.0 | 3.0 | 0.0 | 3.0 | ns |
| t _{IORCKSW} | I/O Clock to R-Clock Skew (FO = 64) (FO = 350) | 0.0 0.0 | 1.7 5.0 | 0.0 0.0 | 1.7 5.0 | 0.0 0.0 | 1.7 5.0 | 0.0 0.0 | 1.7 5.0 | 0.0 0.0 | 5.0 5.0 | ns |
| t _{HRCKSW} | H-Clock to R-Clock Skew (FO = 64) (FO = 350) | 0.0 0.0 | 1.3 3.0 | 0.0 0.0 | 1.0 3.0 | 0.0 0.0 | 1.0 3.0 | 0.0 0.0 | 1.0 3.0 | 0.0 0.0 | 1.0 3.0 | ns |

Notes: *

1. The -2 and -3 speed grades have been discontinued. Refer to PDN 0104, PDN 0203, PDN 0604, and PDN 1004 at http://www.microsemi.com/soc/support/notifications/default.aspx#pdn.

2. Delays based on 35 pF loading.



Pin Descriptions

CLKA Clock A (Input)

Clock input for clock distribution networks. The Clock input is buffered prior to clocking the logic modules. This pin can also be used as an I/O.

CLKB Clock B (Input)

Clock input for clock distribution networks. The Clock input is buffered prior to clocking the logic modules. This pin can also be used as an I/O.

GND Ground

LOW supply voltage.

HCLK Dedicated (Hard-wired) Array Clock (Input)

Clock input for sequential modules. This input is directly wired to each S-Module and offers clock speeds independent of the number of S-Modules being driven. This pin can also be used as an I/O.

I/O Input/Output (Input, Output)

The I/O pin functions as an input, output, three-state, or bidirectional buffer. Input and output levels are compatible with standard TTL and CMOS specifications. Unused I/O pins are tristated by the Designer Series software.

IOCLK Dedicated (Hard-wired) I/O Clock (Input)

Clock input for I/O modules. This input is directly wired to each I/O module and offers clock speeds independent of the number of I/O modules being driven. This pin can also be used as an I/O.

IOPCL Dedicated (Hard-wired) I/O Preset/Clear (Input)

Input for I/O preset or clear. This global input is directly wired to the preset and clear inputs of all I/O registers. This pin functions as an I/O when no I/O preset or clear macros are used.

MODE Mode (Input)

The MODE pin controls the use of diagnostic pins (DCLK, PRA, PRB, SDI). When the MODE pin is HIGH, the special functions are active. When the MODE pin is LOW, the pins function as I/Os. To provide Actionprobe capability, the MODE pin should be terminated to GND through a 10K resistor so that the MODE pin can be pulled high when required.

NC No Connection

This pin is not connected to circuitry within the device.

PRA Probe A (Output)

The Probe A pin is used to output data from any user-defined design node within the device. This independent diagnostic pin can be used in conjunction with the Probe B pin to allow real-time diagnostic output of any signal path within the device. The Probe A pin can be used as a user-defined I/O when debugging has been completed. The pin's probe capabilities can be permanently disabled to protect programmed design confidentiality. PRA is accessible when the MODE pin is HIGH. This pin functions as an I/O when the MODE pin is LOW.

PRB Probe B (Output)

The Probe B pin is used to output data from any user-defined design node within the device. This independent diagnostic pin can be used in conjunction with the Probe A pin to allow real-time diagnostic output of any signal path within the device. The Probe B pin can be used as a user-defined I/O when debugging has been completed. The pin's probe capabilities can be permanently disabled to protect programmed design confidentiality. PRB is accessible when the MODE pin is HIGH. This pin functions as an I/O when the MODE pin is LOW.

SDI Serial Data Input (Input)

Serial data input for diagnostic probe and device programming. SDI is active when the MODE pin is HIGH. This pin functions as an I/O when the MODE pin is LOW.



SDO Serial Data Output (Output)

Serial data output for diagnostic probe. SDO is active when the MODE pin is High. This pin functions as an I/O when the MODE pin is Low.

DCLK Diagnostic Clock (Input)

Clock input for diagnostic probe and device programming. DCLK is active when the MODE pin is HIGH. This pin functions as an I/O when the MODE pin is LOW.

VCC 5 V Supply Voltage

HIGH supply voltage.



3 – Package Pin Assignments

PL84



Note: This is the top view of the package.

Note



| | | PL84 | |
|------------|------------------------|------------------------|------------------------|
| Pin Number | A1415, A14V15 Function | A1425, A14V25 Function | A1440, A14V40 Function |
| 1 | VCC | VCC | VCC |
| 2 | GND | GND | GND |
| 3 | VCC | VCC | VCC |
| 4 | PRA, I/O | PRA, I/O | PRA, I/O |
| 11 | DCLK, I/O | DCLK, I/O | DCLK, I/O |
| 12 | SDI, I/O | SDI, I/O | SDI, I/O |
| 16 | MODE | MODE | MODE |
| 27 | GND | GND | GND |
| 28 | VCC | VCC | VCC |
| 40 | PRB, I/O | PRB, I/O | PRB, I/O |
| 41 | VCC | VCC | VCC |
| 42 | GND | GND | GND |
| 43 | VCC | VCC | VCC |
| 45 | HCLK, I/O | HCLK, I/O | HCLK, I/O |
| 52 | SDO | SDO | SDO |
| 53 | IOPCL, I/O | IOPCL, I/O | IOPCL, I/O |
| 59 | VCC | VCC | VCC |
| 60 | VCC | VCC | VCC |
| 61 | GND | GND | GND |
| 68 | VCC | VCC | VCC |
| 69 | GND | GND | GND |
| 74 | IOCLK, I/O | IOCLK, I/O | IOCLK, I/O |
| 83 | CLKA, I/O | CLKA, I/O | CLKA, I/O |
| 84 | CLKB, I/O | CLKB, I/O | CLKB, I/O |

- 1. All unlisted pin numbers are user I/Os.
- 2. NC denotes no connection.
- 3. MODE should be terminated to GND through a 10K resistor to enable Actionprobe usage; otherwise it can be terminated directly to GND.

PQ100



Note: This is the top view of the package.

Note



| Package | Pin Assignments |
|---------|-----------------|
|---------|-----------------|

| | PQ100 | |
|------------|----------------|----------------|
| Pin Number | A1415 Function | A1425 Function |
| 2 | IOCLK, I/O | IOCLK, I/O |
| 14 | CLKA, I/O | CLKA, I/O |
| 15 | CLKB, I/O | CLKB, I/O |
| 16 | VCC | VCC |
| 17 | GND | GND |
| 18 | VCC | VCC |
| 19 | GND | GND |
| 20 | PRA, I/O | PRA, I/O |
| 27 | DCLK, I/O | DCLK, I/O |
| 28 | GND | GND |
| 29 | SDI, I/O | SDI, I/O |
| 34 | MODE | MODE |
| 35 | VCC | VCC |
| 36 | GND | GND |
| 47 | GND | GND |
| 48 | VCC | VCC |
| 61 | PRB, I/O | PRB, I/O |
| 62 | GND | GND |
| 63 | VCC | VCC |
| 64 | GND | GND |
| 65 | VCC | VCC |
| 67 | HCLK, I/O | HCLK, I/O |
| 77 | SDO | SDO |
| 78 | IOPCL, I/O | IOPCL, I/O |
| 79 | GND | GND |
| 85 | VCC | VCC |
| 86 | VCC | VCC |
| 87 | GND | GND |
| 96 | VCC | VCC |
| 97 | GND | GND |

- 1. All unlisted pin numbers are user I/Os.
- 2. NC denotes no connection.
- 3. MODE should be terminated to GND through a 10K resistor to enable Actionprobe usage; otherwise it can be terminated directly to GND.

PQ160



Note: This is the top view of the package

Note



| | | PQ160 | |
|------------|------------------------|------------------------|------------------------|
| Pin Number | A1425, A14V25 Function | A1440, A14V40 Function | A1460, A14V60 Function |
| 1 | GND | GND | GND |
| 2 | SDI, I/O | SDI, I/O | SDI, I/O |
| 5 | NC | I/O | I/O |
| 9 | MODE | MODE | MODE |
| 10 | VCC | VCC | VCC |
| 14 | NC | I/O | I/O |
| 15 | GND | GND | GND |
| 18 | VCC | VCC | VCC |
| 19 | GND | GND | GND |
| 20 | NC | I/O | I/O |
| 24 | NC | I/O | I/O |
| 27 | NC | I/O | I/O |
| 28 | VCC | VCC | VCC |
| 29 | VCC | VCC | VCC |
| 40 | GND | GND | GND |
| 41 | NC | I/O | I/O |
| 43 | NC | I/O | I/O |
| 45 | NC | I/O | I/O |
| 46 | VCC | VCC | VCC |
| 47 | NC | I/O | I/O |
| 49 | NC | I/O | I/O |
| 51 | NC | I/O | I/O |
| 53 | NC | I/O | I/O |
| 58 | PRB, I/O | PRB, I/O | PRB, I/O |
| 59 | GND | GND | GND |
| 60 | VCC | VCC | VCC |
| 62 | HCLK, I/O | HCLK, I/O | HCLK, I/O |
| 63 | GND | GND | GND |
| 74 | NC | I/O | I/O |
| 75 | VCC | VCC | VCC |
| 76 | NC | I/O | I/O |
| 77 | NC | I/O | I/O |
| 78 | NC | I/O | I/O |
| 79 | SDO | SDO | SDO |
| 80 | IOPCL, I/O | IOPCL, I/O | IOPCL, I/O |
| 81 | GND | GND | GND |
| 90 | VCC | VCC | VCC |
| 91 | VCC | VCC | VCC |

Accelerator Series FPGAs – ACT 3 Family

| | | PQ160 | |
|------------|------------------------|------------------------|------------------------|
| Pin Number | A1425, A14V25 Function | A1440, A14V40 Function | A1460, A14V60 Function |
| 92 | NC | I/O | I/O |
| 93 | NC | I/O | I/O |
| 98 | GND | GND | GND |
| 99 | VCC | VCC | VCC |
| 100 | NC | I/O | I/O |
| 103 | GND | GND | GND |
| 107 | NC | I/O | I/O |
| 109 | NC | I/O | I/O |
| 110 | VCC | VCC | VCC |
| 111 | GND | GND | GND |
| 112 | VCC | VCC | VCC |
| 113 | NC | I/O | I/O |
| 119 | NC | I/O | I/O |
| 120 | IOCLK, I/O | IOCLK, I/O | IOCLK, I/O |
| 121 | GND | GND | GND |
| 124 | NC | I/O | I/O |
| 127 | NC | I/O | I/O |
| 136 | CLKA, I/O | CLKA, I/O | CLKA, I/O |
| 137 | CLKB, I/O | CLKB, I/O | CLKB, I/O |
| 138 | VCC | VCC | VCC |
| 139 | GND | GND | GND |
| 140 | VCC | VCC | VCC |
| 141 | GND | GND | GND |
| 142 | PRA, I/O | PRA, I/O | PRA, I/O |
| 143 | NC | I/O | I/O |
| 145 | NC | I/O | I/O |
| 147 | NC | I/O | I/O |
| 149 | NC | I/O | I/O |
| 151 | NC | I/O | I/O |
| 153 | NC | I/O | I/O |
| 154 | VCC | VCC | VCC |
| 160 | DCLK, I/O | DCLK, I/O | DCLK, I/O |

- 1. All unlisted pin numbers are user I/Os.
- 2. NC denotes no connection.
- 3. MODE should be terminated to GND through a 10K resistor to enable Actionprobe usage; otherwise it can be terminated directly to GND.



PQ208, RQ208



Note: This is the top view of the package

Note



| PQ208, RQ208 | | | PQ208, RQ208 | | | |
|--------------|---------------------------|-----------------------------|--------------|---------------------------|-----------------------------|--|
| Pin Number | A1460, A14V60 Function | A14100, A14V100 Function | Pin Number | A1460, A14V60 Function | A14100, A14V100 Function | |
| 1 | GND | GND | 115 | VCC | VCC | |
| 2 | SDI, I/O | SDI, I/O | 116 | NC | I/O | |
| 11 | MODE | MODE | 129 | GND | GND | |
| 12 | VCC | VCC | 130 | VCC | VCC | |
| 25 | VCC | VCC | 131 | GND | GND | |
| 26 | GND | GND | 132 | VCC | VCC | |
| 27 | VCC | VCC | 145 | VCC | VCC | |
| 28 | GND | GND | 146 | GND | GND | |
| 40 | VCC | VCC | 147 | NC | I/O | |
| 41 | VCC | VCC | 148 | VCC | VCC | |
| 52 | GND | GND | 156 | IOCLK, I/O | IOCLK, I/O | |
| 53 | NC | I/O | 157 | GND | GND | |
| 60 | VCC | VCC | 158 | NC | I/O | |
| 65 | NC | I/O | 164 | VCC | VCC | |
| 76 | PRB, I/O | PRB, I/O | 180 | CLKA, I/O | CLKA, I/O | |
| 77 | GND | GND | 181 | CLKB, I/O | CLKB, I/O | |
| 78 | VCC | VCC | 182 | VCC | VCC | |
| 79 | GND | GND | 183 | GND | GND | |
| 80 | VCC | VCC | 184 | VCC | VCC | |
| 82 | HCLK, I/O | HCLK, I/O | 185 | GND | GND | |
| 98 | VCC | VCC | 186 | PRA, I/O | PRA, I/O | |
| 102 | NC | I/O | 195 | NC | I/O | |
| 103 | SDO | SDO | 201 | VCC | VCC | |
| 104 | IOPCL, I/O | IOPCL, I/O | 205 | NC | I/O | |
| 105 | GND | GND | 208 | DCLK, I/O | DCLK, I/O | |
| 114 | VCC | VCC | | | • | |

- 1. All unlisted pin numbers are user I/Os.
- 2. NC denotes no connection.
- 3. MODE should be terminated to GND through a 10K resistor to enable Actionprobe usage; otherwise it can be terminated directly to GND.



TQ176



Note: This is the top view.

Note



| | TQ176 | | | TQ176 | |
|------------|---------------------------|---------------------------|------------|---------------------------|---------------------------|
| Pin Number | A1440, A14V40 Function | A1460, A14V60 Function | Pin Number | A1440, A14V40 Function | A1460, A14V60 Function |
| 1 | GND | GND | 89 | GND | GND |
| 2 | SDI, I/O | SDI, I/O | 98 | VCC | VCC |
| 10 | MODE | MODE | 99 | VCC | VCC |
| 11 | VCC | VCC | 108 | GND | GND |
| 20 | NC | I/O | 109 | VCC | VCC |
| 21 | GND | GND | 110 | GND | GND |
| 22 | VCC | VCC | 119 | NC | I/O |
| 23 | GND | GND | 121 | NC | I/O |
| 32 | VCC | VCC | 122 | VCC | VCC |
| 33 | VCC | VCC | 123 | GND | GND |
| 44 | GND | GND | 124 | VCC | VCC |
| 49 | NC | I/O | 132 | IOCLK, I/O | IOCLK, I/O |
| 51 | NC | I/O | 133 | GND | GND |
| 63 | NC | I/O | 138 | NC | I/O |
| 64 | PRB, I/O | PRB, I/O | 152 | CLKA, I/O | CLKA, I/O |
| 65 | GND | GND | 153 | CLKB, I/O | CLKB, I/O |
| 66 | VCC | VCC | 154 | VCC | VCC |
| 67 | VCC | VCC | 155 | GND | GND |
| 69 | HCLK, I/O | HCLK, I/O | 156 | VCC | VCC |
| 82 | NC | I/O | 157 | PRA, I/O | PRA, I/O |
| 83 | NC | I/O | 158 | NC | I/O |
| 87 | SDO | SDO | 170 | NC | I/O |
| 88 | IOPCL, I/O | IOPCL, I/O | 176 | DCLK, I/O | DCLK, I/O |

- 1. All unlisted pin numbers are user I/Os.
- 2. NC denotes no connection.
- 3. MODE should be terminated to GND through a 10K resistor to enable Actionprobe usage; otherwise it can be terminated directly to GND.



VQ100



Note: This is the top view.

Note

Accelerator Series FPGAs – ACT 3 Family

| VQ100 | | | | |
|------------|------------------------|------------------------|------------------------|--|
| Pin Number | A1415, A14V15 Function | A1425, A14V25 Function | A1440, A14V40 Function | |
| 1 | GND | GND | GND | |
| 2 | SDI, I/O | SDI, I/O | SDI, I/O | |
| 7 | MODE | MODE | MODE | |
| 8 | VCC | VCC | VCC | |
| 9 | GND | GND | GND | |
| 20 | VCC | VCC | VCC | |
| 21 | NC | I/O | I/O | |
| 34 | PRB, I/O | PRB, I/O | PRB, I/O | |
| 35 | VCC | VCC | VCC | |
| 36 | GND | GND | GND | |
| 37 | VCC | VCC | VCC | |
| 39 | HCLK, I/O | HCLK, I/O | HCLK, I/O | |
| 49 | SDO | SDO | SDO | |
| 50 | IOPCL, I/O | IOPCL, I/O | IOPCL, I/O | |
| 51 | GND | GND | GND | |
| 57 | VCC | VCC | VCC | |
| 58 | VCC | VCC | VCC | |
| 67 | VCC | VCC | VCC | |
| 68 | GND | GND | GND | |
| 69 | GND | GND | GND | |
| 74 | NC | I/O | I/O | |
| 75 | IOCLK, I/O | IOCLK, I/O | IOCLK, I/O | |
| 87 | CLKA, I/O | CLKA, I/O | CLKA, I/O | |
| 88 | CLKB, I/O | CLKB, I/O | CLKB, I/O | |
| 89 | VCC | VCC | VCC | |
| 90 | VCC | VCC | VCC | |
| 91 | GND | GND | GND | |
| 92 | PRA, I/O | PRA, I/O | PRA, I/O | |
| 93 | NC | I/O | I/O | |
| 100 | DCLK, I/O | DCLK, I/O | DCLK, I/O | |

- 1. All unlisted pin numbers are user I/Os.
- 2. NC denotes no connection.
- 3. MODE should be terminated to GND through a 10K resistor to enable Actionprobe usage; otherwise it can be terminated directly to GND.



CQ132



Note: This is the top view

Note



| | CQ132 | CQ132 | | |
|------------|----------------|------------|----------------|--|
| Pin Number | A1425 Function | Pin Number | A1425 Function | |
| 1 | NC | 67 | NC | |
| 2 | GND | 74 | GND | |
| 3 | SDI, I/O | 75 | VCC | |
| 9 | MODE | 78 | VCC | |
| 10 | GND | 89 | VCC | |
| 11 | VCC | 90 | GND | |
| 22 | VCC | 91 | VCC | |
| 26 | GND | 92 | GND | |
| 27 | VCC | 98 | IOCLK, I/O | |
| 34 | NC | 99 | NC | |
| 36 | GND | 100 | NC | |
| 42 | GND | 101 | GND | |
| 43 | VCC | 106 | GND | |
| 48 | PRB, I/O | 107 | VCC | |
| 50 | HCLK, I/O | 116 | CLKA, I/O | |
| 58 | GND | 117 | CLKB, I/O | |
| 59 | VCC | 118 | PRA, I/O | |
| 63 | SDO | 122 | GND | |
| 64 | IOPCL, I/O | 123 | VCC | |
| 65 | GND | 131 | DCLK, I/O | |
| 66 | NC | 132 | NC | |

- 1. All unlisted pin numbers are user I/Os.
- 2. NC denotes no connection.
- 3. MODE should be terminated to GND through a 10K resistor to enable Actionprobe usage; otherwise it can be terminated directly to GND.



CQ196



Note: This is the top view.

Note



| | CQ196 | CQ196 | | |
|------------|----------------|------------|----------------|--|
| Pin Number | A1460 Function | Pin Number | A1460 Function | |
| 1 | GND | 101 | GND | |
| 2 | SDI, I/O | 110 | VCC | |
| 11 | MODE | 111 | VCC | |
| 12 | VCC | 112 | GND | |
| 13 | GND | 137 | VCC | |
| 37 | GND | 138 | GND | |
| 38 | VCC | 139 | GND | |
| 39 | VCC | 140 | VCC | |
| 51 | GND | 148 | IOCLK, I/O | |
| 52 | GND | 149 | GND | |
| 59 | VCC | 155 | VCC | |
| 64 | GND | 162 | GND | |
| 77 | HCLK, I/O | 172 | CLKA, I/O | |
| 79 | PRB, I/O | 173 | CLKB, I/O | |
| 86 | GND | 174 | PRA, I/O | |
| 94 | VCC | 183 | GND | |
| 98 | GND | 189 | VCC | |
| 99 | SDO | 193 | GND | |
| 100 | IOPCL, I/O | 196 | DCLK, I/O | |

- 1. All unlisted pin numbers are user I/Os.
- 2. NC denotes no connection.
- 3. MODE should be terminated to GND through a 10K resistor to enable Actionprobe usage; otherwise it can be terminated directly to GND.



CQ256



Note: This is the top view.

Note



| | CQ256 | CQ256 | | |
|------------|-----------------|------------|-----------------|--|
| Pin Number | A14100 Function | Pin Number | A14100 Function | |
| 1 | GND | 141 | VCC | |
| 2 | SDI, I/O | 158 | GND | |
| 11 | MODE | 159 | VCC | |
| 28 | VCC | 160 | GND | |
| 29 | GND | 161 | VCC | |
| 30 | VCC | 174 | VCC | |
| 31 | GND | 175 | GND | |
| 46 | VCC | 176 | GND | |
| 59 | GND | 188 | IOCLK, I/O | |
| 90 | PRB, I/O | 189 | GND | |
| 91 | GND | 219 | CLKA, I/O | |
| 92 | VCC | 220 | CLKB, I/O | |
| 93 | GND | 221 | VCC | |
| 94 | VCC | 222 | GND | |
| 96 | HCLK, I/O | 223 | VCC | |
| 110 | GND | 224 | GND | |
| 126 | SDO | 225 | PRA, I/O | |
| 127 | IOPCL, I/O | 240 | GND | |
| 128 | GND | 256 | DCLK, I/O | |

- 1. All unlisted pin numbers are user I/Os.
- 2. NC denotes no connection.
- 3. MODE should be terminated to GND through a 10K resistor to enable Actionprobe usage; otherwise it can be terminated directly to GND.



BG225



Note: This is the top view.

Note


| BG225 | |
|----------------|---|
| A1460 Function | Location |
| CLKA or I/O | C8 |
| CLKB or I/O | B8 |
| DCLK or I/O | B2 |
| GND | A1, A15, D15, F8, G7, G8, G9, H6, H7, H8, H9, H10, J7, J8, J9, K8, P2, R15 |
| HCLK or I/O | P9 |
| IOCLK or I/O | B14 |
| IOPCL or I/O | P14 |
| MODE | D1 |
| NC | A11, B5, B7, D8, D12, F6, F11, H1, H12, H14, K11, L1, L13, N8, P5, R1, R8, R11, R14 |
| PRA or I/O | A7 |
| PRB or I/O | L7 |
| SDI or I/O | D4 |
| SDO | N13 |
| VCC | A8, B12, D5, D14, E3, E8, E13, H2, H3, H11, H15, K4, L2, L12, M8, M15, P4, P8, R13 |

- 1. All unlisted pin numbers are user I/Os.
- 2. NC denotes no connection.
- 3. MODE should be terminated to GND through a 10K resistor to enable Actionprobe usage; otherwise it can be terminated directly to GND.
- 4. The BG225 package has been discontinued.



BG313



Note: This is the top view.

Note

| | BG313 | |
|-----------------------------|---|--|
| A14100, A14V100 Function | Location | |
| CLKA or I/O | J13 | |
| CLKB or I/O | G13 | |
| DCLK or I/O | B2 | |
| GND | A1, A25, AD2, AE25, J21, L13, M12, M14, N11, N13, N15, P12, P14, R13 | |
| HCLK or I/O | T14 | |
| IOCLK or I/O | B24 | |
| IOPCL or I/O | AD24 | |
| MODE | G3 | |
| NC | A3, A13, A23, AA5, AA9, AA23, AB2, AB4, AB20, AC13, AC25, AD22, AE1, AE21, B14, C5, C25, D4, D24, E3, E21, F6, F10, F16, G1, G25, H18, H24, J1, J7, J25, K12, L15, L17, M6, N1, N5, N7, N21, N23, P20, R11, T6, T8, U9, U13, U21, V16, W7, Y20, Y24 | |
| PRA or I/O | H12 | |
| PRB or I/O | AD12 | |
| SDI or I/O | C1 | |
| SDO | AE23 | |
| VCC | AB18, AD6, AE13, C13, C19, E13, G9, H22, K8, K20, M16, N3, N9, N25, U5, W13, V2, V22, V24 | |

- 1. All unlisted pin numbers are user I/Os.
- 2. NC denotes no connection.
- 3. MODE should be terminated to GND through a 10K resistor to enable Actionprobe usage; otherwise it can be terminated directly to GND.







Note



| | PG100 | | |
|----------------|--|--|--|
| A1415 Function | Location | | |
| CLKA or I/O | C7 | | |
| CLKB or I/O | D6 | | |
| DCLK or I/O | C4 | | |
| GND | C3, C6, C9, E9, F3, F9, J3, J6, J8, J9 | | |
| HCLK or I/O | H6 | | |
| IOCLK or I/O | C10 | | |
| IOPCL or I/O | К9 | | |
| MODE | C2 | | |
| PRA or I/O | A6 | | |
| PRB or I/O | L3 | | |
| SDI or I/O | B3 | | |
| SDO | L9 | | |
| VCC | B6, B10, E11, F2, F10, G2, K2, K6, K10 | | |

- 1. All unlisted pin numbers are user I/Os.
- 2. NC denotes no connection.
- 3. MODE should be terminated to GND through a 10K resistor to enable Actionprobe usage; otherwise it can be terminated directly to GND.
- 4. The PG100 package has been discontinued.





Note: This is the top view.

Note

| PG133 | | |
|----------------|--|--|
| A1425 Function | Location | |
| CLKA or I/O | D7 | |
| CLKB or I/O | B6 | |
| DCLK or I/O | D4 | |
| GND | A2, C3, C7, C11, C12, F10, G3, G11, L3, L7, L11, M3, N12 | |
| HCLK or I/O | К7 | |
| IOCLK or I/O | C10 | |
| IOPCL or I/O | L10 | |
| MODE | E3 | |
| NC | A1, A7, A13, G1, G13, N1, N7, N13 | |
| PRA or I/O | A6 | |
| PRB or I/O | L6 | |
| SDI or I/O | C2 | |
| SDO | M11 | |
| VCC | B2, B7, B12, E11, G2, G12, J2, J12, M2, M7, M12 | |

- 1. All unlisted pin numbers are user I/Os.
- 2. NC denotes no connection.
- 3. MODE should be terminated to GND through a 10K resistor to enable Actionprobe usage; otherwise it can be terminated directly to GND.
- 4. The PG133 package has been discontinued.





Note: This is the top view.

Note

| | PG175 | | |
|----------------|--|--|--|
| A1440 Function | Location | | |
| CLKA or I/O | C9 | | |
| CLKB or I/O | A9 | | |
| DCLK or I/O | D5 | | |
| GND | D4, D8, D11, D12, E4, E14, H4, H12, L4, L12, M4, M8, M12 | | |
| HCLK or I/O | R8 | | |
| IOCLK or I/O | E12 | | |
| IOPCL or I/O | P13 | | |
| MODE | F3 | | |
| NC | A1, A2, A15, B2, B3, P2, P14, R1, R2, R14, R15 | | |
| PRA or I/O | B8 | | |
| PRB or I/O | R7 | | |
| SDI or I/O | D3 | | |
| SDO | N12 | | |
| VCC | C3, C8, C13, E15, H3, H13, L1, L14, N3, N8, N13 | | |

- 1. All unlisted pin numbers are user I/Os.
- 2. NC denotes no connection.
- 3. MODE should be terminated to GND through a 10K resistor to enable Actionprobe usage; otherwise it can be terminated directly to GND.
- 4. The PG175 package has been discontinued.





Note: This is the top view.

Note

| | PG207 | |
|----------------|--|--|
| A1460 Function | Location | |
| CLKA or I/O | К1 | |
| CLKB or I/O | J3 | |
| DCLK or I/O | E4 | |
| GND | C14, D4, D5, D9, D14, J4, J14, P3, P4, P7, P9, P14, R15 | |
| HCLK or I/O | J15 | |
| IOCLK or I/O | P5 | |
| IOPCL or I/O | N14 | |
| MODE | D7 | |
| NC | A1, A2, A16, A17, B1, B17, C1, C2, S1, S3, S17, T1, T2, T16, T17 | |
| PRA or I/O | H1 | |
| PRB or I/O | K16 | |
| SDI or I/O | C3 | |
| SDO | P15 | |
| VCC | B2, B9, B16, D11, J2, J16, P12, S2, S9, S16, T5 | |

- 1. All unlisted pin numbers are user I/Os.
- 2. NC denotes no connection.
- 3. MODE should be terminated to GND through a 10K resistor to enable Actionprobe usage; otherwise it can be terminated directly to GND.





Note: This is the top view.

Note

For Package Manufacturing and Environmental information, visit the Resource Center at http://www.microsemi.com/soc/products/solutions/package/docs.aspx

3-32

| PG257 | |
|-----------------|---|
| A14100 Function | Location |
| CLKA or I/O | L4 |
| CLKB or I/O | L5 |
| DCLK or I/O | E4 |
| GND | B16, C4, D4, D10, D16, E11, J5, K4, K16, L15, R4, T4, T10, T16, T17, X7 |
| HCLK or I/O | J16 |
| IOCLK or I/O | T5 |
| IOPCL or I/O | R16 |
| MODE | A5 |
| NC | E5 |
| PRA or I/O | J1 |
| PRB or I/O | J17 |
| SDI or I/O | B4 |
| SDO | R17 |
| VCC | C3, C10, C13, C17, K3, K17, V3, V7, V10, V17, X14 |

- 1. All unlisted pin numbers are user I/Os.
- 2. NC denotes no connection.
- 3. MODE should be terminated to GND through a 10K resistor to enable Actionprobe usage; otherwise it can be terminated directly to GND.



4 – Datasheet Information

List of Changes

The following table lists critical changes that were made in each version of the datasheet.

| Revision | Changes | Page |
|--------------------------------|--|-----------------|
| Revision 3 (January 2012) | The description for SDO pins had earlier been removed from the datasheet and has now been included again, in the "Pin Descriptions" section (SAR 35820). | 2-21 |
| | SDO pin numbers had earlier been removed from package pin assignment tables in the datasheet, and have now been restored to the pin tables (SAR 35820). | 3-1 |
| Revision 2 (September 2011) | The ACT 3 datasheet was formatted newly in the style used for current datasheets. The same information is present (other than noted in the list of changes for this revision) but divided into chapters. | N/A |
| | The datasheet was revised to note in multiple places that speed grades -2 and -3 have been discontinued. The following device/package combinations have been discontinued for all speed grades and temperatures (SAR 33872): A1415 PG100 A1425 PG133 A1440 PG175 A1460 BG225 Refer to PDN 0104, PDN 0203, PDN 0604, and PDN 1004. | I and others |
| | The "Features" section was revised to state the clock-to-ouput time and on-chip performance for -1 speed grade as 9.0 ns and 186 MHz. The "General Description" section was revised in accordance (SAR 33872). | I |
| | The maximum performance values were updated in Table 1 • ACT 3 Family Product Information, and now reflect worst-case commercial for the -1 speed grade (SAR 33872). | I |
| | The "Product Plan" table was updated as follows to conform to current offerings (SAR 33872): The A1415A device is offered in PL84, PG100, and VQ100 packages for Military application. The A1440A device is offered in TQ176 and VQ100 packages for Industrial application. | Ш |
| | Table 1-1 • Chip-to-Chip Performance (worst-case commercial) was updated to include data for all speed grades instead of only –3 (SAR 33872). | 1-2 |
| | Figure 1-1 • Predictable Performance (worst-case commercial, –1 speed grade) was revised to reflect values for the –1 speed grade (SAR 33872). | 1-1 |
| | Figure 2-10 • Timing Model was updated to show data for the –1 speed grade instead of –3 (SAR 33872). | 2-16 |
| | Table 2-14 • Logic Module and Routing Delay by Fanout (ns); Worst-Case Commercial Conditions was updated to include data for all speed grades instead of only –3 (SAR 33872). | 2-20 |
| | Package names used in the "Package Pin Assignments" section and throughout the document were revised to match standards given in <i>Package Mechanical Drawings</i> (SAR 27395). | 3-1 |



| Revision | Changes | Page |
|---------------------------|--|------|
| Revision 2 (continued) | In the "Package Pin Assignments" section, notes were added to the pin tables for the following packages, stating that they are discontinued: | |
| | "BG225" | 3-20 |
| | "PG100" | 3-24 |
| | "PG133" | 3-26 |
| | "PG175" | 3-28 |
| Revision 1 (June 2006) | RoHS compliant information was added to the "Ordering Information" section. | II |

Datasheet Categories

Categories

In order to provide the latest information to designers, some datasheet parameters are published before data has been fully characterized from silicon devices. The data provided for a given device is designated as either "Product Brief," "Advance," "Preliminary," or "Production." The definitions of these categories are as follows:

Product Brief

The product brief is a summarized version of a datasheet (advance or production) and contains general product information. This document gives an overview of specific device and family information.

Advance

This version contains initial estimated information based on simulation, other products, devices, or speed grades. This information can be used as estimates, but not for production. This label only applies to the DC and Switching Characteristics chapter of the datasheet and will only be used when the data has not been fully characterized.

Preliminary

The datasheet contains information based on simulation and/or initial characterization. The information is believed to be correct, but changes are possible.

Production

This version contains information that is considered to be final.

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